

Extremes of Stationary Sequences: Clusters and Spectral Processes

JOHAN SEGERS

Université catholique de Louvain
Institut de statistique, biostatistique et sciences actuarielles

Indian Statistical Institute, Kolkata, January 14–15, 2012

Extremes of Stationary Sequences: Clusters and Spectral processes

- I. Clusters of Extremes
- II. Regular Variation and Tail Processes
— joint work with B. BASRAK and T. MEINGUET
- III. Markov Processes
— joint work with A. JANSSEN
- IV. Linear Processes
— joint work with T. MEINGUET

Part I

Clusters of Extremes

An informal view on clusters

For weakly dependent stationary sequences,
extremes arrive in **clusters**.

We are concerned with the asymptotic distribution of the ‘block’

$$(X_1, \dots, X_{r_n})$$

given that at least one ‘extreme value’ occurs

$$\sum_{i=1}^{r_n} I(X_i \text{ hits an exceptional set}) \geq 1 \quad (\text{C})$$

when the expected number of extremes is asymptotically negligible

$$r_n P(X_1 \text{ hits an exceptional set}) = o(1)$$

Formalizing the informal view requires some care

- ▶ The condition (C) is awkward to work with:
when did the extreme value occur for the first time?
- ▶ If the expected number of extremes in a block remains finite, most variables X_i in the block (X_1, \dots, X_{r_n}) will be irrelevant.

Formalizing the notion of a ‘cluster’ therefore requires some care.

Some possibilities:

- ▶ Cluster functionals
- ▶ Cluster distributions
- ▶ Cluster processes

Extremes of Stationary Sequences

Cluster functionals and the cluster map

Approximate cluster distributions

Limit cluster distributions

Beyond the cluster

Cluster statistics

Ingredients

- ▶ Stationary process $(X_n)_n$ on \mathbb{R}
- ▶ High threshold u_n
- ▶ Block size r_n

Interest is in **cluster statistics** of the form

$$c(X_1 - u_n, \dots, X_{r_n} - u_n) \quad \text{conditionally on} \quad M_{r_n} > u_n$$

that only depend on the ‘cluster’:

the stretch between the first and the last exceedance over u_n .

We require that

$$r_n \rightarrow \infty, \quad r_n P(X_1 > u_n) \rightarrow 0$$

Examples of cluster statistics

- ▶ Block maximum: maximal excess

$$c(y_1, \dots, y_{r_n}) = \max(y_1, \dots, y_{r_n})$$

- ▶ Aggregate excess: sum of excesses

$$c(y_1, \dots, y_{r_n}) = \max(y_1, 0) + \dots + \max(y_{r_n}, 0)$$

- ▶ Cluster size: number of excesses

$$c(y_1, \dots, y_{r_n}) = I(y_1 > 0) + \dots + I(y_{r_n} > 0)$$

- ▶ Cluster duration: time span between first and last excess

$$c(y_1, \dots, y_{r_n}) = \max\{i : y_i > 0\} - \min\{i : y_i > 0\} + 1$$

- ▶ Number of threshold upcrossings

$$c(y_1, \dots, y_{r_n}) = I(y_1 > 0) + I(y_1 \leq 0 < y_2) + \dots + I(y_{r_n-1} \leq 0 < y_{r_n})$$

Cluster functionals

Desirable properties of $c(\cdot)$:

- ▶ Its domain is a vector of arbitrary length with at least one non-zero component.
- ▶ It depends only on the ‘extreme’ part of the vector

Definition

A **cluster functional** is a map $c : A \rightarrow \mathbb{R}$ with

$$A = A_1 \cup A_2 \cup \dots$$

$$A_r = \mathbb{R}^r \setminus (-\infty, 0]^r = \{(y_1, \dots, y_r) \in \mathbb{R}^r : \max(y_1, \dots, y_r) > 0\}$$

and neglecting everything that happened before or after the first or last positive value:

$$\begin{aligned}c(y_1, \dots, y_r) &= c(y_\alpha, \dots, y_\omega) \\ \alpha &= \min\{i : y_i > 0\} \\ \omega &= \max\{i : y_i > 0\}\end{aligned}$$

Cluster map

Definition

Recall $\mathbf{A} = \bigcup_{r \geq 1} \mathbf{A}_r$ and $\mathbf{A}_r = \mathbb{R}^r \setminus (-\infty, 0]^r$. Define the **cluster map**

$$\begin{aligned} C : \mathbf{A} &\rightarrow \mathbf{A} : (y_1, \dots, y_r) \mapsto (y_\alpha, \dots, y_\omega) \\ \alpha &= \min\{i : y_i > 0\} \\ \omega &= \max\{i : y_i > 0\} \end{aligned}$$

[Segers 2005]

Then $c : \mathbf{A} \rightarrow \mathbb{R}$ is a cluster functional if and only if

$$c = f \circ C \text{ for some } f : \mathbf{A} \rightarrow \mathbb{R}$$

Hence, to know the asymptotic distribution of cluster statistics, it is sufficient to know the asymptotic distribution of the ‘cluster’ itself

$$C(X_1 - u_n, \dots, X_{r_n} - u_n) \quad \text{conditionally on} \quad M_{r_n} > u_n$$

Extremes of Stationary Sequences

Cluster functionals and the cluster map

Approximate cluster distributions

Limit cluster distributions

Beyond the cluster

Aim: switch to a simpler conditioning event

We are interested in the **cluster distribution**

$$P[C(X_1 - u_n, \dots, X_{r_n} - u_n) \in \cdot \mid M_{r_n} > u_n]$$

Recall $r_n \rightarrow \infty$ and $r_n P(X_1 > u_n) \rightarrow 0$.

The conditioning event $\{M_{r_n} > u_n\}$ is awkward to work with:
when exactly did the exceedances occur?

We'd rather prefer expressions in terms of the law of

$$(X_1, \dots, X_k) \mid X_1 > u_n$$

This would be particularly convenient in the case of Markov chains.

Expected cluster size

Expected number of exceedances given that there is at least one:

$$E \left[\sum_{i=1}^{r_n} I(X_i > u_n) \mid M_{r_n} > u_n \right] = \frac{r_n P(X_1 > u_n)}{P(M_{r_n} > u_n)} =: \frac{1}{\theta_n}$$

so

$$\theta_n = \frac{P(M_{r_n} > u_n)}{r_n P(X_1 > u_n)} \in (0, 1]$$

Example

In the iid case, since $r_n \bar{F}(u_n) \rightarrow 0$, we have

$$\theta_n = \frac{1 - (1 - \bar{F}(u_n))^{r_n}}{r_n \bar{F}(u_n)} \rightarrow 1$$

Finite-cluster condition

Suppose that the impact of a shock is somehow limited in time:

$$\underbrace{X_1, X_2, \dots, X_m}_{>u_n}, \underbrace{X_{m+1}, \dots, X_{r_n}}_{>u_n?}$$
$$\underbrace{X_1, \dots, X_{r_n-m}}_{>u_n?}, X_{r_n-m+1}, \dots, X_{r_n-1}, \underbrace{X_{r_n}}_{>u_n}$$

Formally, put $M_{i,j} = \max(X_i, \dots, X_j)$ and suppose

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} P(M_{m+1, r_n} > u_n \mid X_1 > u_n) = 0 \quad (\text{FiCl1})$$

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} P(M_{1, r_n-m} > u_n \mid X_{r_n} > u_n) = 0 \quad (\text{FiCl2})$$

Sufficient condition:

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} \sum_{i=m+1}^{r_n} P(X_i > u_n \mid X_1 > u_n) = 0 \quad (\text{FiCl})$$

Bounded expected cluster sizes

If (FiCl), the expected cluster size remains bounded:

$$\limsup_{n \rightarrow \infty} \frac{r_n P(X_1 > u_n)}{P(M_{r_n} > u_n)} < \infty$$

$$\text{i.e. } \liminf_{n \rightarrow \infty} \theta_n > 0.$$

Proof: observe that $M_{r_n} \geq \max(X_1, X_{m+1}, X_{2m+1}, \dots, X_{km+1})$ with $k \sim r_n/m$.

The approximant

Consider a bounded, measurable cluster functional $c : \mathbf{A} \rightarrow \mathbb{R}$.
Apply c to different stretches of the process:

$$c_n(i, j) = c(X_i - u_n, \dots, X_j - u_n) \text{ on the event } M_{i,j} > u_n$$

Consider the approximation error

$$\left| \underbrace{E[c_n(1, r_n) \mid M_{r_n} > u_n]}_{\text{quantity of interest}} - \underbrace{\frac{\alpha_{n,m}(c)}{\theta_{n,m}}}_{\text{approximant}} \right|$$

where

$$\begin{aligned} \alpha_{n,m}(c) &= E[c_n(1, m) \mid X_1 > u_n] \\ &\quad - E[c_n(2, m), M_{2,m} > u_n \mid X_1 > u_n] \\ \theta_{n,m} &= P[M_{2,m} \leq u_n \mid X_1 > u_n] \quad \text{'runs'}$$

The cluster approximation

Theorem

If (FiCl), then

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} \left| \underbrace{\theta_{n,m}}_{\text{'runs'}} - \underbrace{\theta_n}_{\text{'blocks'}} \right| = 0$$

as well as

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} \sup_{c: |c| \leq 1} \left| E[c_n(1, r_n) \mid M_{r_n} > u_n] - \frac{\alpha_{n,m}(c)}{\theta_{m,n}} \right| = 0$$

[Segers (2005)]

Proof: elementary calculations, based on careful use of

- ▶ partitionings of the event $\{M_{r_n} > u_n\}$ and similar ones
- ▶ stationarity
- ▶ the cluster property
- ▶ (FiCl)

Main steps in the proof (1)

Consider the first time an exceedance occurs:

$$\begin{aligned} & E[c_n(\mathbf{1}, r_n); M_{r_n} > u_n] \\ &= \sum_{j=1}^{r_n} E[c_n(\mathbf{j}, r_n); M_{j-1} \leq u_n < X_j] \end{aligned}$$

By (FiCl), we can limit the (forward) horizon to m :

$$\dots \approx \sum_{j=1}^{r_n} E[c_n(\mathbf{j}, \mathbf{j} + m - 1); M_{j-1} \leq u_n < X_j]$$

Write each term as a difference by taking out the event $M_{j-1} \leq u_n$:

$$\begin{aligned} & E[c_n(\mathbf{j}, \mathbf{j} + m - 1); X_j > u_n] \\ & - E[c_n(\mathbf{j}, \mathbf{j} + m - 1); M_{j-1} > u_n, X_j > u_n] \end{aligned}$$

By stationarity, the first term is already OK: $j = 1$.

What about the second term?

Main steps in the proof (2)

We need to consider

$$E[c_n(j, j + m - 1); M_{1, j-1} > u_n, X_j > u_n]$$

By (FiCl), we can limit the (backward) horizon to m :

$$\dots \approx E[c_n(j, j + m - 1); M_{j-m, j-1} > u_n, X_j > u_n]$$

By stationarity (set $j = m + 1$), this is

$$\dots = E[c_n(m + 1, 2m + 1); M_{1, m} > u_n, X_{m+1} > u_n]$$

In $\{M_m > u_n\}$, consider the last time an exceedance occurs, apply stationarity, (FiCl), eventually yielding

$$\dots \approx E[c_n(2, m); X_1 > u_n, M_{2, m} > u_n]$$

which is the second term in $\alpha_{n, m}(c)$.

Main steps in the proof (3)

Collect approximations to find that

$$E[c_n(1, r_n); M_{r_n} > u_n] \approx r_n \alpha_{n,m}(c)$$

Consider the special case $c \equiv 1$ to get

$$\theta_{n,m} \approx \theta_n$$

Combine the previous two displays to arrive at the desired approximation.

Without additional effort,
the result is translated in a general framework

- ▶ Measurable state space (S, \mathcal{S})
- ▶ Measurable failure set $B \subset S$
- ▶ $A = \bigcup_{k \geq 1} A_k$ where $A_k = S^k \setminus (S \setminus B)^k$
- ▶ **Cluster map** $C : A \rightarrow A$ is defined by

$$C(x_1, \dots, x_k) = (x_\alpha, \dots, x_\omega)$$

where

- ▶ $\alpha = \min\{i = 1, \dots, k : x_i \in B\}$
- ▶ $\omega = \max\{i = 1, \dots, k : x_i \in B\}$

The general framework encompasses multivariate extremes

Univariate extremes:

- ▶ state space $S = \mathbb{R}$
- ▶ failure set $B = (u, \infty)$

Multivariate extremes:

- ▶ state space $S = \mathbb{R}^d$
- ▶ failure sets $B = \mathbb{R}^d \setminus (-\infty, \mathbf{u}]$ or (\mathbf{u}, ∞) or $\{\mathbf{x} : \|\mathbf{x}\| > u\}$ or ...

What if the failure set is hit at least once?

- ▶ Stationary random vector (X_1, \dots, X_r) in S
- ▶ Assume $P[X_1 \in B] > 0$

Aim

To study the conditional distribution of

$$C(X_1, \dots, X_r) \quad \text{given} \quad \bigcup_{i=1}^r \{X_i \in B\}$$

Cluster functionals and cluster map

A map $c : \mathbf{A} \rightarrow \mathbb{R}$ is a **cluster functional** if it is measurable with respect to the cluster map, i.e.

$$c = f \circ C \quad \text{for some} \quad f : \mathbf{A} \rightarrow \mathbb{R}$$

that is, if

$$c(x_1, \dots, x_r) = c(x_\alpha, \dots, x_\omega)$$

in terms of the first and last hitting times, $1 \leq \alpha \leq \omega \leq r$ of B .

Cluster functionals and the cluster map are equivalent concepts:
for $E \subset \mathbf{A}$,

$$C(x_1, \dots, x_r) \in E \iff \underbrace{I_E \circ C}_{=c}(x_1, \dots, x_r) = 1$$

Extremal index variants

- ▶ Expected number of ‘hits’ of failure set B

$$E \left[\sum_{i=1}^r I\{X_i \in B\} \mid \bigcup_{i=1}^r \{X_i \in B\} \right] = \frac{r P[X_1 \in B]}{P[\bigcup_{i=1}^r \{X_i \in B\}]} = \frac{1}{\theta}$$

- ▶ ‘Hit’ followed/preceded by a ‘run’ of ‘non-hits’ of failure set B

$$\begin{aligned} \theta_m &= P[\bigcap_{i=2}^m \{X_i \notin B\} \mid X_1 \in B] \\ &= P[\bigcap_{i=1}^{m-1} \{X_i \notin B\} \mid X_m \in B], \quad m = 2, \dots, r \end{aligned}$$

- ▶ Compare these with characterizations of extremal index
 - ▶ ‘blocks’ [Leadbetter 1983]
 - ▶ ‘runs’ [O’Brien 1987]
 - ▶ Multivariate extremal index [Nandagopalan 1994]

Approximate cluster distribution

- ▶ \mathcal{C} is set of all cluster functionals $c : \mathbf{A} \rightarrow \mathbb{R}$ such that $|c| \leq 1$
- ▶ Cluster distribution: for $c \in \mathcal{C}$

$$\mu(c) = E[c(X_1, \dots, X_r) \mid \bigcup_{i=1}^r \{X_i \in B\}]$$

- ▶ Approximant: for $c \in \mathcal{C}$

$$\begin{aligned} \mu_m(c) &= \theta^{-1} \left\{ E[c(X_1, \dots, X_m) \mid X_1 \in B] \right. \\ &\quad \left. - E[c(X_2, \dots, X_m) I(\bigcup_{i=2}^m \{X_i \in B\}) \mid X_1 \in B] \right\} \end{aligned}$$

Finite-sample cluster distribution approximation

Quantify (FiCl) via

$$\varepsilon = \max \left\{ P \left[\bigcup_{i=m+1}^r \{X_i \in B\} \mid X_1 \in B \right], \right. \\ \left. P \left[\bigcup_{i=1}^{r-m} \{X_i \in B\} \mid X_r \in B \right] \right\}$$

Theorem

If $m \geq 2$ and $2m + 1 \leq r$,

$$\begin{aligned} \theta &\geq (2m)^{-1}(1 - \varepsilon) \\ |\theta - \theta_m| &\leq \max(m/r, \varepsilon) \\ \sup_{c:|c| \leq 1} |\mu(c) - \mu_m(c)| &\leq \theta^{-1}(4m/r + 5\varepsilon) \end{aligned}$$

[Segers 20xx]

Interpretation: connection between distributions of

- ▶ $C(X_1, \dots, X_r)$ given $\bigcup_{i=1}^r \{X_i \in B\}$
- ▶ (X_1, \dots, X_m) given $\{X_1 \in B\}$

Extremes of Stationary Sequences

Cluster functionals and the cluster map

Approximate cluster distributions

Limit cluster distributions

Beyond the cluster

Asymptotic cluster distribution

- ▶ State space: metric space (S, d)
- ▶ Failure set: non-empty open set $B \subset S$
- ▶ Random triangular array $\{X_{in} : n \geq 1, 1 \leq i \leq r_n\}$ in S
 - ▶ row length $r_n \rightarrow \infty$
 - ▶ every row $(X_{1n}, \dots, X_{r_n n})$ is stationary
 - ▶ $p_n = P[X_{1n} \in B] > 0$
 - ▶ $r_n p_n = E[\sum_{i=1}^{r_n} I(X_{in} \in B)] \rightarrow 0$

Aim

To establish the limiting **cluster distribution**

$$C(X_{1n}, \dots, X_{r_n n}) \quad \text{given} \quad \bigcup_{i=1}^{r_n} \{X_{in} \in B\}$$

with $C : \mathbf{A} \rightarrow \mathbf{A}$ the cluster map and $\mathbf{A} = \bigcup_{r \geq 1} (S^r \setminus (S \setminus B)^r)$

Example

- ▶ State space $S = \mathbb{R}$
- ▶ Failure set $B = \{x : |x| > 1\}$
- ▶ Random variables $X_{in} = X_i/a_n$, $1 \leq i \leq r_n$, with
 - ▶ $(X_i)_{i \geq 1}$ a stationary time series in \mathbb{R}
 - ▶ levels $0 < a_n \rightarrow \infty$ such that $nP[|X_1| > a_n] \rightarrow 1$
 - ▶ block sizes $r_n \rightarrow \infty$ and $r_n = o(n)$
- ▶ Rare events of interest:
 - ▶ $X_{in} \in B$ if and only if $|X_i| > a_n$
 - ▶ $\bigcup_{i=1}^{r_n} \{X_{in} \in B\}$ if and only if $M_{r_n} := \max(|X_1|, \dots, |X_{r_n}|) > a_n$

Problem

To find the asymptotic cluster distribution

$$C(X_1/a_n, \dots, X_{r_n}/a_n) \quad \text{given} \quad M_{r_n} > a_n?$$

Example (continued)

- ▶ Assume that the fidis of $(X_i)_i$ are **multivariate regularly varying**.
- ▶ Then there exists a process $(Y_k)_{k \geq 0}$ such that for every $k \geq 0$,

$$P[(X_1/a_n, \dots, X_{k+1}/a_n) \in \cdot \mid |X_1| > a_n] \xrightarrow{d} P[(Y_0, \dots, Y_k) \in \cdot]$$

- ▶ Conceptually, given $|X_1| > a_n$,

$$\begin{array}{ccccccc} X_1/a_n, & X_2/a_n, & \dots, & X_{k+1}/a_n & & & \\ Y_0, & Y_1, & \dots, & Y_k & & & \\ \text{'present',} & \text{'future'} & & & & & \end{array}$$

- ▶ For Markov chains, the process $(Y_k)_{k \geq 0}$ can typically be written in terms of a random walk

[Rootzén 1988; de Haan et al. 1989; Smith 1992; Perfekt 1994; S. 2007; Resnick and Zeber 2011]

- ▶ Can we express the asymptotic cluster distribution in terms of the **tail process** $(Y_k)_k$?

Assumptions

Tail process

Assume there exists a random sequence $(Y_k)_{k \geq 0}$ called **tail process** in S such that for every $k \geq 0$,

$$P[(X_{1n}, \dots, X_{k+1,n}) \in \cdot \mid X_{1n} \in B] \xrightarrow{d} P[(Y_0, \dots, Y_k) \in \cdot].$$

Also, assume $P[Y_k \in \partial B] = 0$ for all $k \geq 0$.

Finite cluster condition

The impact of a ‘hit’ does not last for too long:

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} P[\bigcup_{i=m+1}^{r_n} \{X_{in} \in B\} \mid X_{1n} \in B] = 0$$

$$\lim_{m \rightarrow \infty} \limsup_{n \rightarrow \infty} P[\bigcup_{i=1}^{r_n - m} \{X_{in} \in B\} \mid X_{r_n n} \in B] = 0$$

Limiting cluster distributions

Theorem

[Segers 20xx] *Under the above assumptions:*

- ▶ *The tail process $(Y_k)_{k \geq 0}$ hits B only finitely often:*

$$Y_0 \in B \quad \text{and} \quad \#\{k \geq 1 : Y_k \in B\} < \infty \quad \text{a.s.}$$

- ▶ *The expected number of hits converges to finite limit:*

$$\begin{aligned} \theta_n &= 1/E[\sum_{i=1}^{r_n} I(X_{in} \in B) \mid \bigcup_{i=1}^{r_n} \{X_{in} \in B\}] \\ &\rightarrow P[\forall k \geq 1 : Y_k \notin B] =: \theta > 0 \end{aligned}$$

- ▶ *The cluster distribution converges:*

$$\begin{aligned} &P[C((X_{in})_{i=1}^{r_n}) \in \cdot \mid \bigcup_{i=1}^{r_n} \{X_i \in B\}] \\ &\xrightarrow{d} \theta^{-1} \left\{ P[C((Y_k)_{k \geq 0}) \in \cdot] \right. \\ &\quad \left. - P[\{C((Y_k)_{k \geq 1}) \in \cdot\} \cap \bigcup_{k \geq 1} \{Y_k \in B\}] \right\} \end{aligned}$$

Extremes of Stationary Sequences

Cluster functionals and the cluster map

Approximate cluster distributions

Limit cluster distributions

Beyond the cluster

The prologue and epilogue of a cluster

- ▶ By definition, the ‘cluster’ starts and ends with the first and last extreme value in a block.
- ▶ What happened just before? What happens next? Maybe there are some ‘less extreme’ but still interesting values.

Aim

To find the (asymptotic) distribution of the *whole* block

$$X_1, \dots, X_r \quad \text{conditionally on} \quad \exists i = 1, \dots, r : X_i \in B$$

Challenges

- ▶ By (FiCl), however, most variables X_i will somehow ‘vanish’ asymptotically.
- ▶ The interesting observations will occur at some random time instant in the middle of the block.

Framework

- ▶ Metric space (S, d)
- ▶ Failure set $B = \{x \in S : d(x, q) > 1\}$ for some $q \in S$
- ▶ Random triangular array $\{X_{in} : n \geq 1, 1 \leq i \leq r_n\}$ in S
 - ▶ row length $r_n \rightarrow \infty$
 - ▶ stationary rows $(X_{1n}, \dots, X_{r_n n})$
 - ▶ failure probability $p_n = P[d(X_{1n}, q) > 1] > 0$
 - ▶ $r_n p_n = E[\sum_{i=1}^{r_n} I\{d(X_{in}, q) > 1\}] \rightarrow 0$
- ▶ The point q acts as a ‘black hole’ for non-extreme values

Example

- ▶ $S = \mathbb{R}^d$
 $q = 0$
 $B = \{x \in \mathbb{R}^d : |x| > 1\}$
- ▶ $X_{in} = X_i/a_n$ for some sequence $0 < a_n \rightarrow \infty$

Problem statement

Aim

To find the limit distribution of quantities defined in terms of $(X_{1n}, \dots, X_{r_n n})$ given $\bigcup_{i=1}^{r_n} I\{d(X_{in}, q) > 1\}$?

Example

Cluster point process N_n on $S \setminus \{q\}$:

$$N_n = \sum_{i=1}^{r_n} \delta_{X_{in}} \quad \text{given} \quad \bigcup_{i=1}^{r_n} \{d(X_{in}, q) > 1\}$$

Cluster process

On the event $\bigcup_{i=1}^{r_n} \{d(X_{in}, q) > 1\}$:

- ▶ **First hitting time** $\alpha_n = \min\{i = 1, \dots, r_n : d(X_{in}, q) > 1\}$
- ▶ **Cluster process** $\xi_n = (\xi_{n,t})_{t \in \mathbb{Z}}$

$$\xi_{n,t} = \begin{cases} X_{\alpha_n+t,n} & \text{if } 1 \leq \alpha_n + t \leq r_n \\ q & \text{otherwise} \end{cases}$$

Intuitively, the vector $(X_{1n}, \dots, X_{r_n n})$ is

- ▶ ‘anchored’ at the first hitting time α_n of the failure set;
- ▶ extended on the left and on the right by the constant sequence (q)

$$\begin{aligned} & \dots, q, X_{1n}, \dots, X_{\alpha_n-1,n}, X_{\alpha_n,n}, X_{\alpha_n+1,n}, \dots, X_{r_n,n}, q, \dots \\ & \dots, \xi_{n,-\alpha_n}, \xi_{n,-\alpha_n+1}, \dots, \xi_{n,-1}, \xi_{n,0}, \xi_{n,1}, \dots, \xi_{n,r_n-\alpha_n+1}, \xi_{n,r_n-\alpha_n}, \dots \end{aligned}$$

Mathematical problem statement

To establish weak convergence of the cluster process ξ_n in the space (\mathbb{E}, ρ) , where

$$\begin{aligned}\mathbb{E} &= \{x \in S^{\mathbb{Z}} : d(x_0, q) > 1 \text{ and } x_t \rightarrow q \text{ as } t \rightarrow \pm\infty\} \\ \rho(x, y) &= \sup_{t \in \mathbb{Z}} d(x_t, y_t)\end{aligned}$$

- ▶ \mathbb{E} is the space of S -valued sequences converging to q .
- ▶ The metric ρ induces the topology of uniform convergence.

Tentative application: point process convergence

Since the cluster point process N_n on $S \setminus \{q\}$ admits the representation

$$N_n = \sum_{i=1}^{r_n} \delta_{X_{in}} = T(\xi_n)$$

for a continuous map

$$\begin{aligned} T : (\mathbb{E}, e) &\rightarrow M_p(S \setminus \{q\}) \\ (x_t)_{t \in \mathbb{Z}} &\mapsto \sum_{t \in \mathbb{Z}} \delta_{x_t} \end{aligned}$$

point process convergence would follow
from weak convergence of ξ_n in \mathbb{E}

Tentative application: cluster functionals

Recall $\mathbf{A} = \bigcup_{r \geq 1} \mathbf{A}_r$ and $\mathbf{A}_r = \{(x_1, \dots, x_r) : \max_j d(x_j, q) > 1\}$

- ▶ disjoint union
- ▶ product topology

Consider the projection map

$$\begin{aligned} \pi : \mathbb{E} &\rightarrow \mathbf{A} \\ (x_t)_t &\mapsto (x_\alpha, \dots, x_\omega) \\ &\alpha(x) = \min\{t : d(x_t, q) > 1\} \\ &\omega(x) = \max\{t : d(x_t, q) > 1\} \end{aligned}$$

Since π is continuous, weak convergence in \mathbb{E} of $\xi_n = (\xi_{n,t})_t$ would imply weak convergence in \mathbf{A} of the cluster

$$\pi(\xi_n) = (X_{\alpha,n}, \dots, X_{\omega,n})$$

Assumption: tail process

Assume there exists a random sequence $(Y_t)_{t \in \mathbb{Z}}$ in S such that for every integer $k \geq 0$,

$$P[(X_{1n}, \dots, X_{2k+1,n}) \in \cdot \mid d(X_{k+1,n}, q) > 1] \\ \xrightarrow{d} P[(Y_{-k}, \dots, Y_k) \in \cdot]$$

Schematically, we have

$$\begin{array}{ccc} X_{1n}, \dots, X_{k,n}, & X_{k+1,n}, & X_{k+2,n}, \dots, X_{2k+1,n} \\ \xrightarrow{d} & Y_{-k}, \dots, Y_{-1}, & Y_0, & Y_1, \dots, Y_k \\ & \text{'past'} & \text{'present'} & \text{'future'} \end{array}$$

Also, assume $P[d(Y_t, q) = 1] = 0$ for all $t \in \mathbb{Z}$.

Assumption: finite-cluster condition

For all $\delta > 0$, as $m \rightarrow \infty$,

$$\left. \begin{array}{l} \limsup_{n \rightarrow \infty} P[\bigcup_{i=m+1}^{r_n} \{d(X_{in}, q) > \delta\} \mid d(X_{1n}, q) > 1] \\ \limsup_{n \rightarrow \infty} P[\bigcup_{i=1}^{r_n - m} \{d(X_{in}, q) > \delta\} \mid d(X_{r_n n}, q) > 1] \end{array} \right\} \rightarrow 0$$

This will ensure, among others, that $\lim_{|t| \rightarrow \infty} Y_t = q$ a.s.

Weak convergence of the cluster process

Theorem

When the tail process exists and the finite-cluster condition holds,

- ▶ the tail sequence $(Y_t)_{t \in \mathbb{Z}}$ hits the failure set finitely often:

$$P[d(Y_0, q) > 1, Y_t \rightarrow q \text{ as } t \rightarrow \pm\infty] = 1$$

- ▶ with positive probability, the tail process hits the failure set for the first time at $t = 0$:

$$\theta = P[\forall t \leq -1 : d(Y_t, q) \leq 1] > 0$$

- ▶ the cluster process converges weakly in \mathbb{E} :

$$\begin{aligned} P[\xi_n \in \cdot \mid \bigcup_{i=1}^n \{d(X_{in}, q) > 1\}] \\ \xrightarrow{d} P[(Y_t)_{t \in \mathbb{Z}} \in \cdot \mid \forall t \leq -1 : d(Y_t, q) \leq 1] \end{aligned}$$

Corollary: Point process convergence

Under the conditions of the theorem,

$$N_n \xrightarrow{d} N$$

in $M_p(S \setminus \{q\})$, where

$$\begin{aligned} N_n &\stackrel{d}{=} \sum_{i=1}^{r_n} \delta_{X_{in}} \quad \text{given} \quad \bigcup_{i=1}^{r_n} \{d(X_{in}, q) > 1\} \\ N &\stackrel{d}{=} \sum_{t \in \mathbb{Z}} \delta_{Y_t} \quad \text{given} \quad \bigcap_{t \leq -1} \{d(Y_t, q) \leq 1\} \end{aligned}$$

Corollary: Convergence of cluster stretches

Recall the cluster map $C : \mathbf{A} \rightarrow \mathbf{A}$,

with $\mathbf{A} = \bigcup_{r \geq 1} \mathbf{A}_r$ and $\mathbf{A}_r = \{(x_1, \dots, x_r) \in S^r : \max_j d(x_j, q) > 1\}$.

Under the conditions of the theorem, we have

$$\begin{aligned} C(X_{1n}, \dots, X_{rnn}) &= (X_{\alpha_n, n}, \dots, X_{\omega_n, n}) \\ &\xrightarrow{d} [(Y_0, \dots, Y_\tau) \text{ given } \forall t \leq -1 : d(Y_t, q) \leq 1] \\ &\quad \text{with } \tau = \max\{t \in \mathbb{Z} : d(Y_t, q) > 1\} \end{aligned}$$

How does this relate to previous results on cluster functionals?

Linking up with cluster functional theory

For a bounded, continuous cluster functional $c : \mathbf{A} \rightarrow \mathbb{R}$,

$$\begin{aligned} & E[c(X_{1n}, \dots, X_{r_n n}) \mid \exists i = 1, \dots, r_n : d(X_{in}, q) > 1] \\ \rightarrow & E[c(Y_0, \dots, Y_\tau) \mid \forall t \leq -1 : d(Y_t, q) \leq 1] \\ = & E[c((Y_t)_{t \geq 0}) \mid \forall t \leq -1 : d(Y_t, q) \leq 1] \\ = & \frac{E[c((Y_t)_{t \geq 0}); \forall t \leq -1 : d(Y_t, q) \leq 1]}{P[\forall t \leq -1 : d(Y_t, q) \leq 1]} \\ = & \frac{1}{\theta} \{E[c((Y_t)_{t \geq 0})] - E[c((Y_t)_{t \geq 0}); \exists t \leq -1 : d(Y_t, q) > 1]\} \end{aligned}$$

However, by the earlier limiting-cluster-distribution theorem,

$$\begin{aligned} & E[c(X_{1n}, \dots, X_{r_n n}) \mid \exists i = 1, \dots, r_n : d(X_{in}, q) > 1] \\ \rightarrow & \frac{1}{\theta} \{E[c((Y_t)_{t \geq 0})] - E[c((Y_t)_{t \geq 1}); \exists t \geq 1 : d(Y_t, q) > 1]\} \end{aligned}$$

Equality follows from a ‘time-change formula’.

Summary: Cluster of extremes

- ▶ Description via cluster functionals or the cluster map
- ▶ General state space
- ▶ Change of conditioning event:
 - From: Conditional distribution of an excited block
 - To: Conditional distribution of a stretch given an excited initial value
- ▶ Approximate cluster distributions
- ▶ Limiting cluster distributions if the tail process exists
- ▶ Looking beyond the cluster: convergence in sequence space
 - ▶ First hitting time serves as time origin

Part II

Regular Variation and Tail Processes
— with B. Basrak and T. Meinguet

Tail processes and spectral processes: Concise descriptions of extremal dependence

- ▶ **Point processes of extremes** [Davis & Hsing 1995; Davis & Mikosch 1998; Basrak & S. 2009]
- ▶ **Cluster functionals** [Yun 2000; S. 2003]
- ▶ **Extremograms** [Davis & Mikosch 2009]
- ▶ **Empirical tail processes** [Drees & Rootzén 2010]
- ▶ **Joint survival functions, tail dependence coefficients** [S. 2007; Meinguet & S. 2010]
- ▶ **Large deviations** [Mikosch & Wintenberger 2012a,b]
- ▶ **Central limit theorems with non-Gaussian stable limits**
[Barkiewicz et al. 2011; Basrak, Krizmanić & S. 2012]
- ▶ ...

Time series of random functions: Dependence over space in time

Physical quantity observed in space and over time

$$X_t(x) = \text{value at time } t \text{ at location } x$$

Space coordinate x varies over a grid – *high-dimensional!*

Think of x as varying continuously over space

↪ For fixed t , view $X_t(\cdot)$ as a *random function*

↪ Time series $(X_t(\cdot))_{t \in \mathbb{Z}}$ of random functions

Goal: to model

Space – cross-sectional tail dependence

Time – clusters

The proper function space depends on the context

- ▶ Maximal temperature over $S \subset [0, 1]^2$:

$$\sup_{x \in S} X_t(x)$$

↪ Space of $C([0, 1]^2)$ of *continuous functions*

- ▶ Aggregated rainfall over $S \subset [0, 1]^2$:

$$\int_S X_t(x) dx$$

↪ Space $L^1([0, 1]^2)$ of *integrable functions*

Extremes of Stationary Sequences

Describing heavy tails: Regular variation

Tail and spectral processes

Time-change formula

Using the spectral process

Conclusion

Regular variation

Heavy tails: **power-law** behaviour

Mathematical description: **regular variation**

| <i>space</i> | <i>tail</i> |
|----------------|---------------------------------|
| \mathbb{R} | $x \rightarrow \infty$ |
| \mathbb{R} | $ x \rightarrow \infty$ |
| \mathbb{R}^d | $\max_j x_j \rightarrow \infty$ |
| \mathbb{R}^d | $\ x\ \rightarrow \infty$ |
| \mathbb{B} | $\ x\ \rightarrow \infty$ |

Defining regular variation

Regular variation can be defined/characterized in multiple ways:

- ▶ limits of functions
- ▶ vague/ M_0 convergence of measures on punctured spaces
- ▶ weak convergence of finite measures on the unit sphere
- ▶ weak convergence of conditional probability distributions

To study regular variation of time series and clustering extremes, the latter view is quite convenient:

1. On \mathbb{R} , at ∞
2. On \mathbb{R} , at $\pm\infty$
3. On \mathbb{R}^d
4. On a Banach space \mathbb{B}

Regular variation at infinity is equivalent to weak convergence of relative excesses

A rv X is **regularly varying (RV) at infinity** with index $\alpha > 0$ if

$$\lim_{u \rightarrow \infty} \frac{P(X > uy)}{P(X > u)} = y^{-\alpha}, \quad y > 0$$

For $y \geq 1$, this is can be written as

$$\lim_{u \rightarrow \infty} P(X/u > y \mid X > u) = y^{-\alpha} = P(Y > u)$$

$\text{RV}(\alpha) \Leftrightarrow$ *weak convergence of relative excesses*:

$$\mathcal{L}(X/u \mid X > u) \xrightarrow{d} \mathcal{L}(Y) = \text{Pareto}(\alpha), \quad u \rightarrow \infty$$

Regular variation on the real line is equivalent to weak convergence of certain conditional distributions (1)

A rv X is **regularly varying** with index $\alpha > 0$ if, as $u \rightarrow \infty$,

$$\frac{P(|X| > uy)}{P(|X| > u)} \rightarrow y^{-\alpha} \quad (y > 0)$$
$$\frac{P(X > u)}{P(|X| > u)} \rightarrow p$$

Equivalent to weak convergence of conditional distributions:

$$\mathcal{L}(|X|/u \mid |X| > u) \xrightarrow{d} \mathcal{L}(Y) \sim \text{Pareto}(\alpha) \quad \text{radius}$$
$$\mathcal{L}(\underbrace{X/|X|}_{\text{sign}(X)} \mid |X| > u) \xrightarrow{d} \mathcal{L}(\Theta) \quad \text{angle}$$

as $u \rightarrow \infty$, where

$$P(\Theta = +1) = p$$
$$P(\Theta = -1) = 1 - p$$

Regular variation on the real line is equivalent to weak convergence of certain conditional distributions (2)

Also jointly: X is RV with index $\alpha > 0$ if, as $u \rightarrow \infty$,

$$\mathcal{L}\left(\frac{|X|}{u}, \frac{X}{|X|} \mid |X| > u\right) \xrightarrow{d} \mathcal{L}(Y, \Theta)$$

where

- ▶ $Y \sim \text{Pareto}(\alpha)$
- ▶ $P(\Theta = +1) = p$
 $P(\Theta = -1) = 1 - p$
- ▶ Y and Θ are independent

Regular variation also equivalent to

$$\mathcal{L}(X/u \mid |X| > u) \xrightarrow{d} \mathcal{L}(Y\Theta)$$

Regular variation in Euclidean space is equivalent to weak convergence of certain conditional distributions (1)

A random vector X in \mathbb{R}^d is **regularly varying** with index $\alpha > 0$ if for all $y > 0$,

$$\frac{P(\|X\| > uy, X/\|X\| \in \cdot)}{P(\|X\| > u)} \xrightarrow{w} y^{-\alpha} H(\cdot), \quad u \rightarrow \infty$$

for some probability measure H on $\mathbb{S}^{d-1} = \{x \in \mathbb{R}^d \mid \|x\| = 1\}$.

Equivalent to weak convergence of conditional distributions:

$$\mathcal{L}(\|X\|/u \mid \|X\| > u) \xrightarrow{d} \mathcal{L}(Y) = \text{Pareto}(\alpha) \quad \text{radius}$$

$$\mathcal{L}(X/\|X\| \mid \|X\| > u) \xrightarrow{d} \mathcal{L}(\Theta) = H \quad \text{angle}$$

as $u \rightarrow \infty$

Weak convergence of the radius and the angle separately implies their weak convergence jointly

For bounded, continuous $f : \mathbb{S}^{d-1} \rightarrow \mathbb{R}$ and for $y \geq 1$, as $u \rightarrow \infty$,

$$\begin{aligned} & E \left[f \left(\frac{X}{\|X\|} \right); \frac{\|X\|}{u} > y \mid \|X\| > u \right] \\ &= E \left[\underbrace{f \left(\frac{X}{\|X\|} \right) \mid \|X\| > uy}_{\rightarrow E[f(\Theta)]} \right] \underbrace{\frac{P(\|X\| > uy)}{P(\|X\| > u)}}_{\rightarrow y^{-\alpha} = P(Y > y)} \\ &\rightarrow E[f(\Theta); Y > y] \end{aligned}$$

for $Y \sim \text{Pareto}(\alpha)$, independent of Θ

Regular variation in Euclidean space is equivalent to weak convergence of certain conditional distributions (2)

A random vector X is RV with index $\alpha > 0$ and angular measure H if

$$\mathcal{L}\left(\frac{\|X\|}{u}, \frac{X}{\|X\|} \mid \|X\| > u\right) \xrightarrow{d} \mathcal{L}(Y, \Theta)$$

where

- ▶ $Y \sim \text{Pareto}(\alpha)$
- ▶ $\Theta \sim H$
- ▶ Y and Θ are independent

Finally, regular variation is also equivalent to

$$\mathcal{L}(X/u \mid \|X\| > u) \xrightarrow{d} \mathcal{L}(Y\Theta), \quad u \rightarrow \infty$$

Regular variation in a Banach space: weak convergence of conditional distributions

Multivariate regular variation in normed spaces: similarly.

[Hult & Lindskog 2005]

A random element X of a Banach space \mathbb{B} is **regularly varying** if

$$\mathcal{L}(X/u \mid \|X\| > u) \xrightarrow{d} \mathcal{L}(Y), \quad u \rightarrow \infty$$

and Y is such that $\|Y\| \geq 1$ is non-degenerate.

Necessarily

- ▶ $\|Y\| \sim \text{Pareto}(\alpha)$ for some $\alpha > 0$
- ▶ $\|Y\|$ and $\Theta = Y/\|Y\|$ are **independent**

and therefore

$$\mathcal{L}\left(\frac{\|X\|}{u}, \frac{X}{\|X\|} \mid \|X\| > u\right) \xrightarrow{d} \mathcal{L}(\|Y\|, \Theta), \quad u \rightarrow \infty$$

For the vague-convergence aficionados: yes you can, but...

Regular variation on Euclidean spaces often defined via vague convergence of measures:

- ▶ Convergence of integrals of continuous functions with compact support
- ▶ Multivariate regular variation on \mathbb{R}^d : for some $V \in RV_{-\alpha}$,

$$\frac{1}{V(u)} P \left[\frac{X}{u} \in \cdot \right] \xrightarrow{v} \mu(\cdot), \quad u \rightarrow \infty.$$

Vague convergence on $[-\infty, +\infty]^d \setminus \{\mathbf{0}\}$

For infinite-dimensional \mathbb{B} , vague convergence collapses:

- ▶ \mathbb{B} not locally compact
- ▶ $f : \mathbb{B} \rightarrow \mathbb{R}$ continuous and compactly supported implies $f \equiv 0$

Replace vague convergence by M_0 -convergence

M_0 -convergence:

“Weak convergence of finite measures on sets bounded away from the origin.”

[Hult & Lindskog 2006]

X is *regularly varying* of index α if for some $V \in RV_{-\alpha}$,

$$\frac{1}{V(u)} P \left[\frac{X}{u} \in \cdot \right] \xrightarrow{M_0} \mu(\cdot), \quad u \rightarrow \infty$$

the limit measure μ being non-null.

Extension to regular variation on star-shaped metric spaces.

Extremes of Stationary Sequences

Describing heavy tails: Regular variation

Tail and spectral processes

Time-change formula

Using the spectral process

Conclusion

Joint regular variation of a time series: What does it mean?

Let \mathbb{B} be a **separable Banach space**

- ▶ E.g. \mathbb{R}^d , $C([0, 1])$, L^p , ℓ^p
- ▶ Separability assumed out of convenience.
Probably not needed everywhere.
Excludes for instance $D([0, 1])$ and spaces of usc functions

Let $(X_t)_{t \in \mathbb{Z}}$ be a **strictly stationary time series** in \mathbb{B} .

- ▶ Law of $(X_{s+h}, \dots, X_{t+h})$ does not depend on h .

Joint regular variation of the *whole* series $(X_t)_{t \in \mathbb{Z}}$?

The raw definition involves a cascade of angular measures

$(X_t)_{t \in \mathbb{Z}}$ is **(jointly) regularly varying** with index $\alpha > 0$
if for all $s \leq t \in \mathbb{Z}$, the vector (X_s, \dots, X_t) in \mathbb{B}^{t-s+1}
is regularly varying with the same index.

Wlog $s = 1 \leq t$. Let H_t be the spectral measure of (X_1, \dots, X_t) :

$$\mathcal{L} \left(\frac{(X_1, \dots, X_t)}{\|(X_1, \dots, X_t)\|} \mid \|(X_1, \dots, X_t)\| > u \right) \xrightarrow{d} H_t, \quad u \rightarrow \infty$$

- ▶ H_t is a probability measure on the unit sphere in \mathbb{B}^t .
- ▶ The measures H_1, H_2, H_3, \dots are linked somehow.
- ▶ Idem for M_0 -convergence to limit measures μ_t .

Changing the conditioning event yields a unique limit object

Let $(X_t)_{t \in \mathbb{Z}}$ be a stationary time series in \mathbb{B} and let $\alpha > 0$.

Theorem

The following statements are equivalent:

- (i) $(X_t)_{t \in \mathbb{Z}}$ is regularly varying with index α .
- (ii) The function $u \mapsto P(\|X_0\| > u)$ belongs to $RV_{-\alpha}$ and

$$\mathcal{L}((X_t/\|X_0\|)_{t \in \mathbb{Z}} \mid \|X_0\| > u) \xrightarrow{d} (\Theta_t)_{t \in \mathbb{Z}} \quad (u \rightarrow \infty)$$

- (iii) For $Y \sim \text{Pareto}(\alpha)$ independent from some $(\Theta_t)_{t \in \mathbb{Z}}$,

$$\mathcal{L}(\|X_0\|/u, (X_t/\|X_0\|)_{t \in \mathbb{Z}} \mid \|X_0\| > u) \xrightarrow{d} (Y, (\Theta_t)_{t \in \mathbb{Z}}) \quad (u \rightarrow \infty)$$

- (iv) For $Y \sim \text{Pareto}(\alpha)$ independent from some $(\Theta_t)_{t \in \mathbb{Z}}$,

$$\mathcal{L}((X_t/u)_{t \in \mathbb{Z}} \mid \|X_0\| > u) \xrightarrow{d} (Y\Theta_t)_{t \in \mathbb{Z}} \quad (u \rightarrow \infty)$$

Reconstructing the M_0 -limit measures from the spectral process or tail process

- ▶ **Spectral process:** the unique limit process $(\Theta_t)_{t \in \mathbb{Z}}$ in (ii)–(iv).
- ▶ **Tail process:** the process $Y_t = Y\Theta_t$ in (iii)

The M_0 -limit in \mathbb{B}^t punctured at the origin

$$\frac{1}{P(\|X_0\| > u)} P[(X_1/u, \dots, X_t/u) \in \cdot] \xrightarrow{M_0} \mu_t \quad (u \rightarrow \infty)$$

is given by

$$\int_{\mathbb{B}^t} f d\mu_t = \sum_{j=1}^t \int_0^\infty E \left[f(0, \dots, 0, r\Theta_0, \dots, r\Theta_{t-j}) \right. \\ \left. I \left(\max_{-j+1 \leq i \leq -1} \|\Theta_i\| = 0 \right) \right] d(-r^{-\alpha})$$

The spectral process versus the spectral measure

- ▶ Special case $t = 0$:

$$\mathcal{L}(X_0/\|X_0\| \mid \|X_0\| > u) \xrightarrow{d} \mathcal{L}(\Theta_0), \quad u \rightarrow \infty$$

so $\mathcal{L}(\Theta_0)$ is the **spectral measure** H_0 of X_0 .

Clearly, $\|\Theta_0\| = 1$.

- ▶ For general $t \in \mathbb{Z}$,

$$\mathcal{L}(X_t/\|X_0\| \mid \|X_0\| > u) \xrightarrow{d} \mathcal{L}(\Theta_t), \quad u \rightarrow \infty$$

so $\|\Theta_t\| \neq 1$ in general if $t \neq 0$.

By stationarity, the spectral measure of X_t is H_0 too.

The tail and spectral processes of a stationary process are in general non-stationary

Example (Independence)

If $(X_t)_{t \in \mathbb{Z}}$ is iid and X_0 is regularly varying,

$$\mathcal{L}((u^{-1}X_t)_{t \in \mathbb{Z}} \mid \|X_0\| > u) \xrightarrow{\text{fidi}} \mathcal{L}(\dots, 0, 0, Y_0, 0, 0, \dots)$$

Example (Full dependence)

If $X_t = X_0$ for all $t \in \mathbb{Z}$ and X_0 is regularly varying,

$$\mathcal{L}((u^{-1}X_t)_{t \in \mathbb{Z}} \mid \|X_0\| > u) \xrightarrow{\text{fidi}} \mathcal{L}(\dots, Y_0, Y_0, Y_0, \dots)$$

Extremes of Stationary Sequences

Describing heavy tails: Regular variation

Tail and spectral processes

Time-change formula

Using the spectral process

Conclusion

Stationarity of $(X_t)_{t \in \mathbb{Z}}$ induces a subtle structure on the tail/spectral process

Claim. $P(\Theta_{-t} \neq 0) = E[\|\Theta_t\|^\alpha]$

Proof – step 1:

Since $Y_{-t} = \|Y_0\| \Theta_{-t}$,

$$\begin{aligned} P(\Theta_{-t} \neq 0) &= P(Y_{-t} \neq 0) \\ &= \lim_{r \rightarrow 0} P(\|Y_{-t}\| > r) \\ &= \lim_{r \rightarrow 0} \lim_{u \rightarrow \infty} P(\|X_{-t}\|/u > r \mid \|X_0\| > u) \end{aligned}$$

Calculate the two limits.

Stationarity of $(X_t)_{t \in \mathbb{Z}}$ induces a subtle structure on the tail/spectral process

Claim. $P(\Theta_{-t} \neq 0) = E[\|\Theta_t\|^\alpha]$

Proof – step 2:

Limit as $u \rightarrow \infty$: By stationarity and regular variation

$$\begin{aligned} & P(\|X_{-t}\|/u > r \mid \|X_0\| > u) \\ &= P(\|X_0\|/u > r \mid \|X_t\| > u) \\ &= \frac{P(\|X_0\| > ur, \|X_t\| > u)}{P(\|X_t\| > u)} \\ &= \underbrace{\frac{P(\|X_0\| > ru)}{P(\|X_t\| > u)}}_{\rightarrow r^{-\alpha}} \underbrace{P(r\|X_t\| > ru \mid \|X_0\| > ru)}_{\rightarrow P(r\|Y_t\| > 1)} \\ &\rightarrow r^{-\alpha} P(r\|Y_t\| > 1) \end{aligned}$$

as $u \rightarrow \infty$.

Stationarity of $(X_t)_{t \in \mathbb{Z}}$ induces a subtle structure on the tail/spectral process

Claim. $P(\Theta_{-t} \neq 0) = E[\|\Theta_t\|^\alpha]$

Proof – step 3:

Limit as $r \rightarrow 0$: Since $Y_t = \|Y_0\|\Theta_t$,

$$\begin{aligned} r^{-\alpha} P(r\|Y_t\| > 1) &= r^{-\alpha} \int_1^\infty P(ry\|\Theta_t\| > 1) d(-y^{-\alpha}) \\ &= \int_0^{r^{-\alpha}} P(\|\Theta_t\|^\alpha > x) dx \\ &\xrightarrow{r \rightarrow 0} \int_0^\infty P(\|\Theta_t\|^\alpha > x) dx = E[\|\Theta_t\|^\alpha] \end{aligned}$$

QED

Forward and backward process:

Restricting the spectral process to the future or the past

A stationary process $(X_t)_{t \in \mathbb{Z}}$ in \mathbb{B} has a **forward** tail process $(Y_t)_{t \geq 0}$ if

$$\mathcal{L}((X_t/u)_{t \geq 0} \mid \|X_0\| > u) \xrightarrow{\text{fidi}} \mathcal{L}((Y_t)_{t \geq 0})$$

Idem: backward tail process, forward/backward spectral process.

The property $P(\Theta_{-t} \neq 0) = E[\|\Theta_t\|^\alpha]$ suggests that we can infer the distribution of the backward process from the forward one.

Time-change formula:

How a time-shift affects the spectral process

Theorem

Statements (ii)–(iv) in the previous theorem are equivalent to the same statements with \mathbb{Z} replaced by \mathbb{Z}_+ or \mathbb{Z}_- .

In that case,

$$E[f(\Theta_{-s}, \dots, \Theta_t)] = E\left[f\left(\frac{\Theta_0}{\|\Theta_s\|}, \dots, \frac{\Theta_{t+s}}{\|\Theta_s\|}\right) \|\Theta_s\|^\alpha I(\|\Theta_s\| > 0)\right]$$

for all nonnegative integer s and t and for all integrable functions $f : \mathbb{B}^{t+s+1} \rightarrow \mathbb{R}$ such that $f(\theta_{-s}, \dots, \theta_t) = 0$ whenever $\theta_{-s} = 0$.

Considering the time-reversed process $\tilde{X}_t = X_{-t}$ yields a similar reduction to the backward spectral process.

Understanding the time-change formula (1)

Assume $\mathbb{B} = \mathbb{R}$, $\alpha = 1$, and $X_t > 0$ a.s., so $\Theta_0 = 1$.

The time-change formula at $s = 1$ and $t = 0$ implies that for integrable $f : [0, \infty) \rightarrow \mathbb{R}$ such that $f(0) = 0$,

$$E[f(\Theta_{-1})] = E[f(1/\Theta_{+1}) \Theta_{+1}]$$

$$E[f(\Theta_{+1})] = E[f(1/\Theta_{-1}) \Theta_{-1}]$$

Let μ be the limit measure of (X_{t-1}, X_t) on $[0, \infty)^2 \setminus \{(0, 0)\}$:

$$\frac{1}{P(X_0 > u)} P[u^{-1}(X_{t-1}, X_t) \in \cdot] \xrightarrow{v} \mu(\cdot) \quad (u \rightarrow \infty)$$

To be applied to both (X_0, X_1) and to (X_{-1}, X_0) :
duality relation between Θ_1 and Θ_{-1} .

Understanding the time-change formula (2)

By definition of μ , Θ_1 and Θ_{-1} (Picture!):

$$\begin{aligned}P(\Theta_1 \leq z) &= \lim_{u \rightarrow \infty} P\left[\frac{X_1}{X_0} \leq z \mid X_0 > u\right] \\&= \lim_{u \rightarrow \infty} \frac{1}{P(X_0 > u)} P\left[\frac{X_1/u}{X_0/u} \leq z, X_0/u > 1\right] \\&= \mu\{(x, y) : y/x \leq z, x > 1\} \\P(\Theta_{-1} \leq z) &= \lim_{u \rightarrow \infty} P\left[\frac{X_0}{X_1} \leq z \mid X_1 > u\right] \\&= \dots \\&= \mu\{(x, y) : x/y \leq z, y > 1\}\end{aligned}$$

Link between Θ_1 and Θ_{-1} follows if we can solve for μ .

Solving for the limit measure

If $f : [0, \infty)^2 \rightarrow \mathbb{R}$ (bounded, continuous) vanishes on $[0, \delta] \times [0, \infty)$,

$$\begin{aligned}\int f d\mu &= \lim_{u \rightarrow \infty} \frac{1}{P(X_0 > u)} E[f(X_0/u, X_1/u)] \\ &= \lim_{u \rightarrow \infty} \frac{P(X_0 > \delta u)}{P(X_0 > u)} E[f(X_0/u, X_1/u) \mid X_0 > \delta u] \\ &= \delta^{-1} E[f(\delta Y_0, \delta Y_1)] \\ &= \delta^{-1} \int_1^\infty E[f(\delta y, \delta y \Theta_1)] d(-y^{-1}) \\ &= \int_\delta^\infty E[f(r, r \Theta_1)] d(-r^{-1}) \\ &= \int_0^\infty E[f(r, r \Theta_1)] d(-r^{-1})\end{aligned}$$

- ▶ Formula extends to f such that $f(0, y) = 0$.
- ▶ For more general f , decompose

$$f(x, y) = \{f(x, y) - f(0, y)\} + f(0, y)$$

Symmetry

μ is symmetric if and only if $\Theta_{-1} \stackrel{d}{=} \Theta_1$.

Example

If μ corresponds to the Hüsler–Reiss max-stable distribution, we have $\Theta_{-1} \stackrel{d}{=} \Theta_1$ Lognormal with unit expectation.

Extremes of Stationary Sequences

Describing heavy tails: Regular variation

Tail and spectral processes

Time-change formula

Using the spectral process

Conclusion

Joint survival function when applying linear functionals

- ▶ Let $\{0, t\} \subset I \subset \{0, \dots, t\}$.
- ▶ For $i \in I$, let $0 \neq b_i^* \in \mathbb{B}^*$, the dual of \mathbb{B}
 - ▶ $b_i^* : \mathbb{B} \rightarrow \mathbb{R}$ linear and bounded

By conditioning on the events $\|X_0\| > u/\|b_0^*\|$ or $\|X_t\| > u/\|b_t^*\|$,

$$\begin{aligned} \lim_{u \rightarrow \infty} \frac{P(\forall i \in I : b_i^* X_i > u)}{P(\|X_0\| > u)} &= E[\min\{(b_i^* \Theta_i)_+^\alpha : i \in I\}] \\ &= E[\min\{(b_i^* \Theta_{i-t})_+^\alpha : i \in I\}] \end{aligned}$$

Equality of the expectations follows from the time-change formula.

Proof via conditioning and the spectral representation

Proof of $\frac{P(\forall i \in I : b_i^* X_i > u)}{P(\|X_0\| > u)} \rightarrow E[\min\{(b_i^* \Theta_i)_+^\alpha : i \in I\}] :$

Step 1: calculate the limit as $u \rightarrow \infty$.

Since $b_0^* X_0 > u$ implies $\|X_0\| > u/\|b_0^*\|$,

$$\begin{aligned} & \frac{P(\forall i \in I : b_i^* X_i > u)}{P(\|X_0\| > u)} \\ &= \frac{P(\|X_0\| > u/\|b_0^*\|)}{P(\|X_0\| > u)} P(\forall i \in I : b_i^* X_i > u \mid \|X_0\| > u/\|b_0^*\|) \\ &\rightarrow \|b_0^*\|^\alpha P(\forall i \in I : b_i^* Y_i > \|b_0^*\|) \end{aligned}$$

Proof via conditioning and the spectral representation

Proof of $\frac{P(\forall i \in I : b_i^* X_i > u)}{P(\|X_0\| > u)} \rightarrow E[\min\{(b_i^* \Theta_i)_+^\alpha : i \in I\}] :$

Step 2: Reduce the tail process to the spectral process.

Recall $Y_i = Y\Theta_i$ with $Y \sim \text{Pareto}(\alpha)$ independent of $(\Theta_i)_i$.

$$\begin{aligned} & \|b_0^*\|^\alpha P(\forall i \in I : b_i^* Y_i > \|b_0^*\|) \\ &= \|b_0^*\|^\alpha \int_1^\infty P(\forall i \in I : b_i^* (y\Theta_i) > \|b_0^*\|) d(-y^{-\alpha}) \\ &= \int_0^{\|b_0^*\|^\alpha} P\{\forall i \in I : (b_i^* \Theta_i)_+^\alpha > u\} du \\ &= \int_0^\infty P\{\forall i \in I : (b_i^* \Theta_i)_+^\alpha > u\} du \\ &= E[\min\{(b_i^* \Theta_i)_+^\alpha : i \in I\}] \end{aligned}$$

using $|b_0^* \Theta_0| \leq \|b_0^*\| \|\Theta_0\| = \|b_0^*\|$.

QED

Joint survival of the sequence of norms

Similarly, for $b_i \in (0, \infty)$,

$$\begin{aligned} \lim_{u \rightarrow \infty} \frac{P(\forall i \in I : b_i \|X_i\| > u)}{P(\|X_0\| > u)} &= E[\min\{b_i^\alpha \|\Theta_i\|^\alpha : i \in I\}] \\ &= E[\min\{b_i^\alpha \|\Theta_{i-t}\|^\alpha : i \in I\}] \end{aligned}$$

Equality of the expectations follows from the time-change formula.

Tail dependence coefficients

The **coefficient of upper tail dependence** between b^*X_0 and b^*X_h , for $b^* \in \mathbb{B}^*$ such that $P(b^*\Theta_0 > 0) > 0$:

$$\begin{aligned}\lim_{u \rightarrow \infty} P(b^*X_h > u \mid b^*X_0 > u) &= \frac{E[\min\{(b^*\Theta_0)_+^\alpha, (b^*\Theta_h)_+^\alpha\}]}{E[(b^*\Theta_0)_+^\alpha]} \\ &= \frac{E[\min\{(b^*\Theta_0)_+^\alpha, (b^*\Theta_{-h})_+^\alpha\}]}{E[(b^*\Theta_0)_+^\alpha]}\end{aligned}$$

The coefficient of tail dependence between $\|X_0\|$ and $\|X_h\|$:

$$\begin{aligned}\lim_{u \rightarrow \infty} P(\|X_h\| > u \mid \|X_0\| > u) &= E[\min(\|\Theta_h\|^\alpha, 1)] \\ &= E[\min(\|\Theta_{-h}\|^\alpha, 1)]\end{aligned}$$

Extremogram

Extremogram: Extreme-value analogue of the correlogram:

$$\rho_{A,B}(h) = \lim_{n \rightarrow \infty} n P(X_0/a_n \in A, X_h/a_n \in B),$$

- ▶ Regions A, B at least one of which stays away from the origin
- ▶ $a_n > 0$ satisfies $nP(\|X_0\| > a_n) \rightarrow 1$ as $n \rightarrow \infty$

[Davis & Mikosch 2009]

If A and B are continuity sets of the distributions of Y_0 and Y_h respectively and if $A \subset \{x \in \mathbb{B} : \|x\| > 1\}$, then

$$\begin{aligned} \rho_{A,B}(h) &= \lim_{n \rightarrow \infty} P(X_0/a_n \in A, X_h/a_n \in B \mid \|X_0\| > a_n) \\ &= P(Y_0 \in A, Y_h \in B). \end{aligned}$$

Extremogram of the image under linear functionals

If

$$A = \{x \in \mathbb{B} : a^*x > 1\},$$

$$B = \{x \in \mathbb{B} : b^*x > 1\}$$

for some $a^*, b^* \in \mathbb{B}^*$, then

$$\begin{aligned}\rho_{A,B}(h) &= \lim_{n \rightarrow \infty} n P(a^*X_0 > a_n, b^*X_h > a_n) \\ &= E[\min\{(a^*\Theta_0)_+^\alpha, (b^*\Theta_h)_+^\alpha\}]\end{aligned}$$

Extremal index of the sequence of norms

The (candidate) extremal index [Leadbetter 1983] of $(\|X_t\|)_{t \in \mathbb{Z}}$:

$$\begin{aligned}\theta &= \lim_{m \rightarrow \infty} \lim_{u \rightarrow \infty} P\left(\max_{t=1, \dots, m} \|X_t\| \leq u \mid \|X_0\| > u\right) \\ &= P\left(\sup_{t \geq 1} \|Y_t\| \leq 1\right) \\ &= E\left[\sup_{t \geq 0} \|\Theta_t\|^\alpha - \sup_{t \geq 1} \|\Theta_t\|^\alpha\right]\end{aligned}$$

Passing from the tail process to the spectral process

Proof of $P(\sup_{t \geq 1} \|Y_t\| \leq 1) = E[\sup_{t \geq 0} \|\Theta_t\|^\alpha - \sup_{t \geq 1} \|\Theta_t\|^\alpha]$:

Writing $Y = \|Y_0\|$, since $Y^{-\alpha} \sim \text{Uniform}(0, 1)$ and since $\|\Theta_0\| = 1$,

$$\begin{aligned} P\left(\sup_{t \geq 1} \|Y_t\| \leq 1\right) &= P\left(Y \sup_{t \geq 1} \|\Theta_t\| \leq 1\right) \\ &= P\left(\sup_{t \geq 1} \|\Theta_t\|^\alpha \leq Y^{-\alpha}\right) \\ &= \int_0^1 P\left(\sup_{t \geq 1} \|\Theta_t\|^\alpha \leq u\right) du \\ &= 1 - E\left[\min\left(1, \sup_{t \geq 1} \|\Theta_t\|^\alpha\right)\right] \\ &= E\left[\sup_{t \geq 0} \|\Theta_t\|^\alpha - \sup_{t \geq 1} \|\Theta_t\|^\alpha\right] \end{aligned}$$

using the identity $\int_0^1 P(\xi \leq u) du = 1 - \int_0^\infty P\{\min(1, \xi) > u\} du$

Extremal index of the image under a linear functional

Let $b^* \in \mathbb{B}^*$ be such that $P(b^* \Theta_0 > 0) > 0$.

The (candidate) **extremal index** of $(b^* X_t)_{t \in \mathbb{Z}}$:

$$\begin{aligned}\theta(b^*) &= \lim_{m \rightarrow \infty} \lim_{u \rightarrow \infty} P\left(\max_{t=1, \dots, m} b^* X_t \leq u \mid b^* X_0 > u\right) \\ &= 1 - \frac{E[\min\{(b^* \Theta_0)_+^\alpha, \sup_{t \geq 1} (b^* \Theta_t)_+^\alpha\}]}{E[(b^* \Theta_0)_+^\alpha]} \\ &= \frac{E[\sup_{t \geq 0} (b^* \Theta_t)_+^\alpha - \sup_{t \geq 1} (b^* \Theta_t)_+^\alpha]}{E[(b^* \Theta_0)_+^\alpha]}\end{aligned}$$

Large deviations and the cluster index

$\mathbb{B} = \mathbb{R}$. Partial sums $S_k = X_1 + \cdots + X_k$.

For $a_n > 0$ such that $n P(|X_0| > a_n) \rightarrow 1$, put

$$b_+(k) = \lim_{n \rightarrow \infty} n P(S_k > a_n)$$

For certain Markov chains, the **cluster index** b_+ exists:

$$b_+ = \lim_{k \rightarrow \infty} \{b_+(k+1) - b_+(k)\} = E \left[\left(\sum_{t \geq 0} \Theta_t \right)_+^\alpha - \left(\sum_{t \geq 1} \Theta_t \right)_+^\alpha \right]$$

Large deviations principle: for appropriate $u_n, v_n \rightarrow \infty$,

$$\lim_{n \rightarrow \infty} \sup_{x \in (u_n, v_n)} \left| \frac{P(S_n > x)}{n P(|X_0| > x)} - b_+ \right| = 0$$

Central limit theorems with stable, non-Gaussian limits

$\mathbb{B} = \mathbb{R}$ and $0 < \alpha < 2$. Partial sums $S_n = X_1 + \cdots + X_n$

- ▶ Stable limits of the partial sums

[Bartkiewicz, Jakubowski, Mikosch, and Wintenberger 2011]

- ▶ Functional limit theorem in $D[0, 1]$ with Skorohod's M_1 topology (weaker than J_1)

[Basrak, Krizmanić & S. 2012]

Limiting characteristic functions (Lévy measures) expressed in terms of spectral process.

Extremes of Stationary Sequences

Describing heavy tails: Regular variation

Tail and spectral processes

Time-change formula

Using the spectral process

Conclusion

To take home...

- 1 Regular variation and existence of the **spectral process**:

$$\mathcal{L}(\|X_0\|/u, (X_t/\|X_0\|)_{t \in \mathbb{Z}} \mid \|X_0\| > u) \xrightarrow{\text{fidi}} \mathcal{L}(Y, (\Theta_t)_{t \in \mathbb{Z}})$$

with $Y \sim \text{Pareto}(\alpha)$ independent of $(\Theta_t)_{t \in \mathbb{Z}}$

- 2 **Time-change formula**:

backward ($t \leq 0$) versus **forward** ($t \geq 0$) spectral process

- 3 **Using** the spectral process for describing **extremal dependence**

Part III

Markov Processes — with A. Janßen

Extremes of Stationary Sequences

Set-up and main finding

Forward spectral processes

Time-change formula

Adjoint distributions

Back-and-forth spectral processes and the spectral process

Set-up: multivariate Markov chain with regularly varying initial distribution

Discrete-time, \mathbb{R}^d -valued random process $(X_t)_{t \geq 0}$ defined by

$$X_t = \Psi(X_{t-1}, \varepsilon_t), \quad t = 1, 2, \dots,$$

where

- ▶ $\varepsilon_1, \varepsilon_2, \dots$ are iid in a measurable space $(\mathbb{E}, \mathcal{E})$, independent of X_0
- ▶ $\Psi : \mathbb{R}^d \times \mathbb{E} \rightarrow \mathbb{R}^d$ is measurable
- ▶ the law of X_0 is **multivariate regularly varying**

If $(X_t)_t$ is stationary, it will be assumed to be defined for all $t \in \mathbb{Z}$.

Commenting the framework:

Representation of the Markov chain

Rather than transition kernels, use the representation

$$X_t = \Psi(X_{t-1}, \varepsilon_t)$$

- ▶ Non-unique
- ▶ General, e.g. inverse (conditional) Rosenblatt (1952) transform
 - ▶ ε_t iid uniform $[0, 1]^d$
 - ▶ $\Psi(x, \cdot)$ vector of (conditional)² quantile functions
- ▶ Arises naturally in examples, e.g. stochastic recurrence equation

$$X_t = A_t X_{t-1} + B_t, \quad \varepsilon_t = (A_t, B_t)$$

Aim: to find the spectral process of a multivariate regularly varying Markov chain

We are looking for the weak limit $(M_t)_t$, called **spectral process**, in

$$\mathcal{L}(\|X_0\|/u, (X_t/\|X_0\|)_t \mid \|X_0\| > u) \xrightarrow{d} \mathcal{L}(Y, (M_t)_t), \quad u \rightarrow \infty$$

- ▶ $\alpha > 0$ is the index of regular variation of X_0
- ▶ Y is Pareto(α), i.e. $P[Y > y] = y^{-\alpha}$ for $y \geq 1$
- ▶ Y is independent of $(M_t)_t$

Continuous mapping theorem:

$$\mathcal{L}((X_t/u)_t \mid \|X_0\| > u) \xrightarrow{d} \mathcal{L}((YM_t)_t), \quad u \rightarrow \infty$$

The spectral process and the extremogram: two sides of the same coin

Linking the **spectral process** and the **extremogram** [Davis & Mikosch 2009]:

- ▶ For nice sets $A, B \subset \mathbb{R}^d$ such that $A \subset \{x : \|x\| \geq 1\}$,

$$\begin{aligned}\rho_{AB}(h) &= \lim_{u \rightarrow \infty} P[u^{-1}X_h \in B \mid u^{-1}X_0 \in A] \\ &= P[YM_h \in B \mid YM_0 \in A], \quad h = 0, 1, 2, \dots\end{aligned}$$

- ▶ Conversely, from the extremogram of the lagged- h process

$$Y_{t,h} = \text{vec}(X_{t-h+1}, \dots, X_t),$$

one deduces the $2hd$ -dimensional distributions of the spectral process.

Main findings

Markov spectral processes $(M_t)_t$ verify the following properties:

- ▶ The forward ($t \geq 0$) and backward ($t \leq 0$) chains are **adjoint**
- ▶ The forward and backward spectral processes are **Markov chains**
- ▶ They enjoy a certain **scaling property**

Univariate case: (to be thought of as) multiplicative random walks

[Smith 1992; Perfekt 1994; Yun 2000; Bortot & Coles 2000/2003; S. 2007; Resnick & Zeber 2011]

General: **back-and-forth tail chain**

Extremes of Stationary Sequences

Set-up and main finding

Forward spectral processes

Time-change formula

Adjoint distributions

Back-and-forth spectral processes and the spectral process

Condition: regularly varying initial distribution

The distribution of X_0 is regularly varying with

- ▶ index $\alpha > 0$
- ▶ *spectral/angular measure* H on the unit sphere \mathbb{S}^{d-1}

$$\mathcal{L}(\|X_0\|/u, X_0/\|X_0\| \mid \|X_0\| > u) \xrightarrow{d} \mathcal{L}(Y, M_0), \quad u \rightarrow \infty$$

where

- ▶ $M_0 \sim H$
- ▶ Y is Pareto(α), i.e. $P[Y > y] = y^{-\alpha}$ for $y \geq 1$
- ▶ Y and M_0 are independent

Condition: asymptotic scaling of the update function

Recall

$$X_t = \Psi(X_{t-1}, \varepsilon_t)$$

1. With probability one and for all H -almost every $s \in \mathbb{S}^{d-1}$,

$$\lim_{u \rightarrow \infty} \frac{\Psi(us(u), \varepsilon_t)}{u} = \phi(s, \varepsilon_t)$$

whenever $s(u) \rightarrow s$ as $u \rightarrow \infty$.

2. If $P[\phi(s, \varepsilon_t) = 0] > 0$ for some s in the support of H , then with probability one,

$$\sup_{\|x\| \leq u} |\Psi(x, \varepsilon_t)| = O(u), \quad u \rightarrow \infty$$

Conditions easily verified in examples such as $X_t = A_t X_{t-1} + B_t$.

Unfolding the recursion

Aim: to find the weak limit M_t , of $X_t/\|X_0\|$, given $\|X_0\| > u \rightarrow \infty$.

If $\|X_0\|$ is 'large':

$$M_0 \stackrel{d}{\approx} \frac{X_0}{\|X_0\|} \sim H$$

$$M_1 \stackrel{d}{\approx} \frac{X_1}{\|X_0\|} = \frac{\Psi(X_0, \varepsilon_1)}{\|X_0\|} \approx \phi\left(\frac{X_0}{\|X_0\|}, \varepsilon_1\right) \stackrel{d}{\approx} \phi(M_0, \varepsilon_1),$$

$$\begin{aligned} M_2 &\stackrel{d}{\approx} \frac{X_2}{\|X_0\|} = \frac{\|X_1\|}{\|X_0\|} \frac{\Psi(X_1, \varepsilon_2)}{\|X_1\|} \\ &\approx \frac{\|X_1\|}{\|X_0\|} \phi\left(\frac{X_1}{\|X_1\|}, \varepsilon_2\right) \\ &= \frac{\|X_1\|}{\|X_0\|} \phi\left(\frac{X_1/\|X_0\|}{\|(X_1/\|X_0\|)\|}, \varepsilon_2\right) \stackrel{d}{\approx} \|M_1\| \phi\left(\frac{M_1}{\|M_1\|}, \varepsilon_2\right) \end{aligned}$$

Existence and description of the forward spectral process

Theorem

For a time-homogeneous Markov chain $(X_t)_{t \geq 0}$, under the previous conditions,

$$\mathcal{L}\left(\frac{\|X_0\|}{u}; \frac{X_0}{\|X_0\|}, \frac{X_1}{\|X_0\|}, \dots \mid \|X_0\| > u\right) \xrightarrow{d} \mathcal{L}(Y; M_0, M_1, \dots)$$

with, for $t \geq 1$,

$$M_t = \|M_{t-1}\| \phi\left(\frac{M_{t-1}}{\|M_{t-1}\|}, \varepsilon_t\right) I_{\{\|M_{t-1}\| > 0\}}$$

and

- ▶ $Y, M_0, \varepsilon_1, \varepsilon_2, \dots$ are independent
- ▶ $Y \sim \text{Pareto}(\alpha)$
- ▶ $M_0 \sim H$
- ▶ $\varepsilon_1, \varepsilon_2, \dots$ iid (copies) as in the definition of (X_t)

Example: vector AR(1) – angular measure

$$X_t = AX_{t-1} + \varepsilon_t, \quad t \geq 0$$

- ▶ deterministic $A \in \mathbb{R}^{d \times d}$ such that $\|A^m\| < 1$ for some $m \geq 1$
- ▶ ε_t iid regularly varying $\alpha > 0$, angular measure λ
- ▶ $X_0, \varepsilon_1, \varepsilon_2, \dots$ independent

Then X_0 is regularly varying with index α too and spectral measure

$$H = \sum_{k \geq 0} p_k \lambda_k$$

- ▶ λ_k the angular measure of $A^k \varepsilon_t$
- ▶ $(p_k)_{k \geq 0}$ a discrete probability distribution given by A , λ and α

See Part IV *Linear processes*.

Example: vector AR(1) – forward tail process

The update function has the asymptotic scaling property:

$$\begin{aligned}\phi(s, \varepsilon_t) &= \lim_{u \rightarrow \infty} \frac{\Psi(us(u), \varepsilon_t)}{u} \\ &= \lim_{u \rightarrow \infty} \frac{A us(u) + \varepsilon_t}{u} \\ &= As, \quad s \in \mathbb{S}^{d-1}\end{aligned}$$

The forward spectral process $(M_t)_{t \geq 0}$ is then simply

$$\begin{aligned}M_t &= \|M_{t-1}\| \phi\left(\frac{M_{t-1}}{\|M_{t-1}\|}, \varepsilon_t\right) \\ &= AM_{t-1} \\ &= \dots \\ &= A^t M_0\end{aligned}$$

Extremes of Stationary Sequences

Set-up and main finding

Forward spectral processes

Time-change formula

Adjoint distributions

Back-and-forth spectral processes and the spectral process

Stationarity: existence of the full spectral process

Suppose in addition that $(X_t)_t$ is *strictly stationary*.

Without loss of generality, assume that X_t is defined for all $t \in \mathbb{Z}$.

Corollary

Under the previous conditions, there exists a process $(M_t)_{t \in \mathbb{Z}}$ s.t.

$$\mathcal{L} \left(\frac{\|X_0\|}{u}; \dots, \frac{X_{-1}}{\|X_0\|}, \frac{X_0}{\|X_0\|}, \frac{X_1}{\|X_0\|}, \dots \mid \|X_0\| > u \right) \\ \xrightarrow{d} \mathcal{L}(Y; \dots, M_{-1}, M_0, M_1, \dots), \quad u \rightarrow \infty$$

Existence of the spectral process and regular variation

- ▶ The fids of the Markov chain $(X_t)_{t \in \mathbb{Z}}$ are regularly varying
- ▶ Existence of the forward spectral process $M_t, t \geq 0$, implies existence of the full spectral process $M_t, t \in \mathbb{Z}$
- ▶ Reconstruct the full spectral process from the forward spectral process via **time-change formulas**

Time-change formula:

Reconstructing the full tail process from the forward part

Corollary

For all integer h, s, t with $s, t \geq 0$ and for every measurable function $f : (\mathbb{R}^d)^{s+1+t} \rightarrow \mathbb{R}$ satisfying $f(x_{-s}, \dots, x_t) = 0$ whenever $x_0 = 0$,

$$\begin{aligned} E[f(M_{-s-h}, \dots, M_{t-h})] \\ = E \left[f \left(\frac{M_{-s}}{\|M_h\|}, \dots, \frac{M_t}{\|M_h\|} \right) \|M_h\|^\alpha I_{\{\|M_h\| > 0\}} \right] \end{aligned}$$

[Basrak & S. 2009, Theorem 3.1(iii)]

- ▶ Change in distribution due to a time-shift of lag $h \in \mathbb{Z}$
- ▶ Choosing $s = 0 \leq h$ yields at the right-hand side an expression that depends on the forward tail process only

Extremes of Stationary Sequences

Set-up and main finding

Forward spectral processes

Time-change formula

Adjoint distributions

Back-and-forth spectral processes and the spectral process

Recapitulation

- $(X_t)_t$ regularly varying Markov chain in \mathbb{R}^d
- Ψ update function: $X_t = \Psi(X_{t-1}, \varepsilon_t)$
- ϕ scaling limit: $\Psi(x, \varepsilon_t) \approx \|x\| \phi(\frac{x}{\|x\|}, \varepsilon_t)$ if $\|x\|$ is large
- Y Pareto(α) random variable
weak limit of $\|X_0\|/u$ given $\|X_0\| > u$ as $u \rightarrow \infty$
 $\alpha > 0$ is the index of regular variation of $\|X_0\|$
- M_t spectral process
weak limit of $X_t/\|X_0\|$ given $\|X_0\| > u$ as $u \rightarrow \infty$
- H spectral/angular measure of X_0
law of M_0 , taking values in $\mathbb{S}^{d-1} = \{x : \|x\| = 1\}$

How to reconstruct the backward spectral process?

For Markov spectral processes $(M_t)_t$:

- ▶ The **forward** spectral process admitted an explicit representation:

$$M_t = \|M_{t-1}\| \phi\left(\frac{M_{t-1}}{\|M_{t-1}\|}, \varepsilon_t\right) I_{\{\|M_{t-1}\| > 0\}}, \quad t \geq 1$$

- ▶ By the time-change formula,
the law of the **backward** spectral process ($t \leq 0$)
is determined by the **forward** spectral process ($t \geq 0$)

*How does the **backward** spectral process look like?*

A first step: let us study the law of (M_{-1}, M_0) . Recall:

$$\mathcal{L}(X_{-1}/\|X_0\| \mid \|X_0\| > u) \xrightarrow{d} \mathcal{L}(M_{-1}), \quad u \rightarrow \infty$$

A special case of the time-change formula motivates an adjoint relation between probability measures

The distributions of (M_0, M_1) and (M_0, M_{-1}) are “adjoint”.

- ▶ In the time-change formula, set $s = 0$ and $h = t = 1$:

$$E[f(M_{-1}, M_0)] = E\left[f\left(\frac{M_0}{\|M_1\|}, \frac{M_1}{\|M_1\|}\right) \|M_1\|^\alpha I_{\{\|M_1\|>0\}}\right]$$

for all $f : (\mathbb{R}^d)^2 \rightarrow \mathbb{R}$ satisfying $f(y_0, y_1) = 0$ whenever $y_0 = 0$

- ▶ Similarly, set $s = 1, h = -1$ and $t = 0$:

$$E[f(M_0, M_1)] = E\left[f\left(\frac{M_{-1}}{\|M_{-1}\|}, \frac{M_0}{\|M_{-1}\|}\right) \|M_{-1}\|^\alpha I_{\{\|M_{-1}\|>0\}}\right]$$

for all $f : (\mathbb{R}^d)^2 \rightarrow \mathbb{R}$ such that $f(y_{-1}, y_0) = 0$ whenever $y_0 = 0$

Admissible distributions for the definition of the adjoint

The adjoint relation will be defined on a certain set \mathcal{M}_α of **probability measures** P on $\mathbb{S}^{d-1} \times \mathbb{R}^d$.

- Think of P as the law of (M_0, M_1) or (M_0, M_{-1}) .

By definition, P belongs to \mathcal{M}_α if for every Borel set $S \subset \mathbb{S}^{d-1}$

$$\int_{\mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})} I\left(\frac{m}{\|m\|} \in S\right) \|m\|^\alpha P(ds, dm) \leq P(S \times \mathbb{R}^d)$$

We call \mathcal{M}_α the set of **admissible distributions**.

In particular, setting $S = \mathbb{S}^{d-1}$ yields

$$\int_{\mathbb{S}^{d-1} \times \mathbb{R}^d} \|m\|^\alpha P(ds, dm) \leq 1$$

Tail chain distributions are admissible

Let $(M_t)_{t \in \mathbb{Z}}$ be the spectral process of a regularly varying stationary Markov chain $(X_t)_{t \in \mathbb{Z}}$ as before.

Lemma

The law of (M_0, M_1) belongs to \mathcal{M}_α , i.e.

$$E \left[I \left(\frac{M_1}{\|M_1\|} \in S \right) \|M_1\|^\alpha \right] \leq P(M_0 \in S)$$

for every Borel set $S \subset \mathbb{S}^{d-1}$.

In particular, setting $S = \mathbb{S}^{d-1}$ gives

$$E[\|M_1\|^\alpha] \leq 1$$

An adjoint relation between probability measures

For $P \in \mathcal{M}_\alpha$, define a signed Borel measure P^* on $\mathbb{S}^{d-1} \times \mathbb{R}^d$ by:

- ▶ Restriction to $\mathbb{S}^{d-1} \times \{0\}$: for $S \subset \mathbb{S}^{d-1}$,

$$\begin{aligned} & P^*(S \times \{0\}) \\ &= P(S \times \mathbb{R}^d) - \int_{\mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})} I\left(\frac{m}{\|m\|} \in S\right) \|m\|^\alpha P(ds, dm) \end{aligned}$$

- ▶ Restriction to $\mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})$: for $E \subset \mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})$,

$$P^*(E) = \int_{\mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})} I\left(\left(\frac{m}{\|m\|}, \frac{s}{\|m\|}\right) \in E\right) \|m\|^\alpha P(ds, dm)$$

We call P^* the **adjoint measure** of P in \mathcal{M}_α .

The adjoint is a true ‘adjoint’

Lemma

Let $P \in \mathcal{M}_\alpha$ and let P^* be its adjoint measure.

- (i) P^* is a probability measure.
- (ii) The marginal distributions of P and P^* on \mathbb{S}^{d-1} are the same.
- (iii) $P^* \in \mathcal{M}_\alpha$.
- (iv) $(P^*)^* = P$.
- (v) For every measurable function $f : \mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\}) \rightarrow \mathbb{R}$,

$$\begin{aligned} & \int_{\mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})} f(s^*, m^*) P^*(ds^*, dm^*) \\ &= \int_{\mathbb{S}^{d-1} \times (\mathbb{R}^d \setminus \{0\})} f\left(\frac{m}{\|m\|}, \frac{s}{\|m\|}\right) \|m\|^\alpha P(ds, dm) \end{aligned}$$

The forward and backward increments of the spectral process satisfy the adjoint relation

Let $(M_t)_{t \in \mathbb{Z}}$ be the spectral process of a regularly varying stationary Markov chain $(X_t)_{t \in \mathbb{Z}}$ as before.

Corollary

The distributions of (M_0, M_1) and (M_0, M_{-1}) are adjoint.

Proof: Time-change formula.

Special case:

$$\begin{aligned}P[M_{-1} \neq 0] &= E[\|M_1\|^\alpha], \\P[M_1 \neq 0] &= E[\|M_{-1}\|^\alpha]\end{aligned}$$

Special case: univariate and positive

- ▶ $d = 1, \mathbb{S}^{d-1} = \{-1, 1\}$
- ▶ If $P \in \mathcal{M}_\alpha$ has $P(\{-1\} \times \mathbb{R}) = 0$,
then P must be concentrated on $\{+1\} \times [0, \infty)$
- ▶ Then so is P^* and for $B \subset (0, \infty)$

$$P^*(\{+1\} \times B) = \int_{s=+1, m>0} I\left(\frac{1}{m} \in B\right) m^\alpha P(ds, dm)$$

- ▶ Examples if $\alpha = 1$:
 - ▶ If P is lognormal with unit expectation, then $P = P^*$
 - ▶ If P is Bernoulli, then $P = P^*$
 - ▶ If P is unit exponential,
then P^* is the law of $1/(E_1 + E_2)$, with E_1, E_2 iid unit exponential

Extremes of Stationary Sequences

Set-up and main finding

Forward spectral processes

Time-change formula

Adjoint distributions

Back-and-forth spectral processes and the spectral process

Taking stock

- ▶ Initial state: $M_0 \sim H$ angular measure of X_0
- ▶ Forward spectral process: $M_0, \varepsilon_1, \varepsilon_2, \dots$ are independent and

$$M_j = \|M_{t-1}\| \phi\left(\frac{M_{t-1}}{\|M_{t-1}\|}\right) I_{\{\|M_{t-1}\|>0\}}, \quad t = 1, 2, \dots$$

- ▶ Laws of (M_0, M_1) and (M_0, M_{-1}) are adjoint
- ▶ Time-change formula

How does the backward spectral process $M_t, t \leq 0$, look like?

Back-and-forth spectral process

A process $(M_t)_{t \in \mathbb{Z}}$ in \mathbb{R}^d is called a *back-and-forth tail chain* with index $\alpha \in (0, \infty)$, notation BFTC(α), if:

- (i) $\mathcal{L}(M_0, M_1)$ and $\mathcal{L}(M_0, M_{-1})$ belong to \mathcal{M}_α and are adjoint;
- (ii) the forward chain $(M_t)_{t \geq 0}$ is a Markov chain with respect to the filtration $\sigma(M_s, s \leq t)$, $t \geq 0$, and the Markov kernel satisfies

$$\begin{aligned} & P[M_t \in \cdot \mid M_{t-1} = x_{t-1}] \\ &= \begin{cases} \delta_0(\cdot) & \text{if } x_{t-1} = 0, \\ P[\|x_{t-1}\| M_1 \in \cdot \mid M_0 = x_{t-1}/\|x_{t-1}\|] & \text{if } x_{t-1} \neq 0; \end{cases} \end{aligned}$$

- (iii) the backward chain $(M_{-t})_{t \geq 0}$ is a Markov chain with respect to the filtration $\sigma(M_{-s}, s \leq t)$, $t \geq 0$, and satisfies the same relation as in (ii) with $t - 1$ and t replaced by $-t + 1$ and $-t$ respectively

Time-change formula for a BFTC

Let $(M_t)_{t \in \mathbb{Z}}$ be a BFTC(α).

Theorem

For all integer $s, t \geq 0$ and for all measurable functions $f : \mathbb{R}^{(s+1+t)d} \rightarrow \mathbb{R}$ vanishing on $\{0\} \times \mathbb{R}^{(s+t)d}$, the $s + 1$ numbers

$$E \left[f \left(\frac{M_{-s+h}}{\|M_h\|}, \dots, \frac{M_{t+h}}{\|M_h\|} \right) \|M_h\|^\alpha I_{\{M_h \neq 0\}} \right], \quad h = 0, \dots, s,$$

are all the same, in the sense that if one integral exists, then they all exist and they are equal.

The case $s = 1$ and $t = 0$ is just the adjoint relation between the distributions of (M_0, M_1) and (M_0, M_{-1}) .

Identifying a back-and-forth tail chain from its forward part

Theorem

Let $(Y_t)_{t \in \mathbb{Z}}$ be a process in \mathbb{R}^d and let $(M_t)_{t \in \mathbb{Z}}$ be a BFTC(α) in \mathbb{R}^d .

If

1. $\mathcal{L}(Y_0, \dots, Y_t) = \mathcal{L}(M_0, \dots, M_t)$ for all $t \geq 0$
2. for all $h, s, t \in \mathbb{Z}$ with $s, t \geq 0$ and for all bounded, measurable $f : (\mathbb{R}^d)^{s+1+t} \rightarrow \mathbb{R}$ satisfying $f(y_{-s}, \dots, y_t) = 0$ whenever $y_0 = 0$,

$$E[f(Y_{-s-h}, \dots, Y_{t-h})] = E \left[f \left(\frac{Y_{-s}}{\|Y_h\|}, \dots, \frac{Y_t}{\|Y_h\|} \right) \|Y_h\|^\alpha I_{\{\|Y_h\| > 0\}} \right]$$

then

$$\mathcal{L}(Y_{-s}, \dots, Y_t) = \mathcal{L}(M_{-s}, \dots, M_t), \quad s, t \geq 0.$$

Markov spectral processes are back-and-forth tail chains

Every $(M_t)_{t \in \mathbb{Z}}$ whose **forward part** ($t \geq 0$) has a BFTC(α) structure, must be a **full** ($t \in \mathbb{Z}$) BFTC(α). In particular:

Corollary

The spectral process $(M_t)_{t \in \mathbb{Z}}$ of a regularly varying, stationary Markov chain $(X_t)_{t \in \mathbb{Z}}$ satisfying the earlier conditions is a BFTC(α).

Univariate back-and-forth tail chains are sign-sensitive multiplicative random walks

- ▶ P a law on $\{-1, +1\} \times \mathbb{R}$ in \mathcal{M}_α ; adjoint P^*
- ▶ $(M_t)_{t \in \mathbb{Z}}$ a BFTC(α) with $(M_0, M_1) \sim P$ and $(M_0, M_{-1}) \sim P^*$
- ▶ Then for $t \geq 1$,

$$M_t = \begin{cases} |M_{t-1}|A_t & \text{if } M_{t-1} > 0, \\ 0 & \text{if } M_{t-1} = 0, \\ |M_{t-1}|B_t & \text{if } M_{t-1} < 0; \end{cases}$$

$$M_{-t} = \begin{cases} |M_{-t+1}|A_{-t} & \text{if } M_{-t+1} > 0, \\ 0 & \text{if } M_{-t+1} = 0, \\ |M_{-t+1}|B_{-t} & \text{if } M_{-t+1} < 0; \end{cases}$$

where the increments $A_{\pm t}$ and $B_{\pm t}$ are independent, with laws determined by P and P^* , and independent of $M_0 \in \{-1, 1\}$

‘Tail switching potential’ [Bortot & Coles 2003; S. 2007]

Example: vector AR(1) – back-and-forth tail process

Recall: deterministic $A \in \mathbb{R}^{d \times d}$, iid regularly varying $(\varepsilon_t)_{t \in \mathbb{Z}}$,

$$X_t = AX_{t-1} + \varepsilon_t = \sum_{k \geq 0} A^k \varepsilon_{t-k} \quad t \in \mathbb{Z}$$

$$M_t = A^t M_0 \quad t \geq 0$$

Full BFTC(α):

$$M_{-N+h} = \begin{cases} A^h M_{-N} & \text{if } h \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

where

- ▶ N is a certain random nonnegative integer
- ▶ conditionally on N , the distribution of M_{-N} is determined by A , the angular measure of ε_t , and $\alpha > 0$.

Conclusion: structure of Markov spectral processes

- ▶ **Tail chains** give information on the **extremes** of multivariate regularly varying Markov chains
- ▶ **Markov spectral processes are back-and-forth tail chains:**
 - ▶ The forward and backward spectral processes are **Markov chains** too
 - ▶ The forward ($t \geq 0$) and backward ($t \leq 0$) chains are **adjoint**
 - ▶ They enjoy a certain **scaling property**

Part IV

Linear Processes — with T. Meinguet

Extremes of Stationary Sequences

Introduction

Linear operators and regular variation

Infinite random sums

Linear processes

Example: AR(1) processes

Conclusion

Time series of random functions

Physical quantity observed in space and over time

$$X_t(x) = \text{value at time } t \text{ at location } x$$

Space coordinate x varies over a grid – *high-dimensional!*

Think of x as varying continuously over space

↪ For fixed t , view $X_t(\cdot)$ as a *random function*

↪ Time series $(X_t(\cdot))_{t \in \mathbb{Z}}$ of random functions

Goal: to model **extremal dependence** in

Space – cross-sectional tail dependence

Time – clusters

Example: Autoregressive process

Define $X_t(\cdot)$ recursively by

$$X_t(x) = \int K(x, y) X_{t-1}(y) dy + Z_t(x)$$

Model ingredients:

- ▶ Kernel $K(x, y)$: from location y now to location x tomorrow
- ▶ Z_t iid random functions: innovations – heavy tails!

More general: *linear time series*

Regular variation in a Banach space is weak convergence of conditional distributions

A random element X of a Banach space \mathbb{B} is **regularly varying** if

$$\mathcal{L}(X/u \mid \|X\| > u) \xrightarrow{d} \mathcal{L}(Y), \quad u \rightarrow \infty$$

for Y such that $\|Y\| \geq 1$ is non-degenerate.

Necessarily

- ▶ $\|Y\| \sim \text{Pareto}(\alpha)$ for some $\alpha > 0$
- ▶ $\|Y\|$ and $\Theta = Y/\|Y\|$ are **independent**

and therefore

$$\mathcal{L}\left(\frac{\|X\|}{u}, \frac{X}{\|X\|} \mid \|X\| > u\right) \xrightarrow{d} \mathcal{L}(Y, \Theta), \quad u \rightarrow \infty$$

Linear processes taking values in a Banach space

Two Banach spaces $\mathbb{B}_1, \mathbb{B}_2$.

A **linear process** $(X_t)_{t \in \mathbb{Z}}$ is of the form

$$X_t = \sum_{i \in \mathbb{Z}} T_i(Z_{t-i})$$

where

- ▶ Z_t are iid in \mathbb{B}_1
- ▶ Bounded linear operators $T_i : \mathbb{B}_1 \rightarrow \mathbb{B}_2$

E.g.: AR(1) process ($\mathbb{B}_1 = \mathbb{B}_2$)

$$X_t = T(X_{t-1}) + Z_t = \sum_{i \geq 0} T^i Z_{t-i}$$

Extremes of Stationary Sequences

Introduction

Linear operators and regular variation

Infinite random sums

Linear processes

Example: AR(1) processes

Conclusion

Linear operators preserve regular variation

Let X be a regularly varying random element in \mathbb{B}_1 with index $\alpha > 0$ and spectral measure H and let $A : \mathbb{B}_1 \rightarrow \mathbb{B}_2$ be a bounded linear operator. We have

$$\frac{P(\|AX\| > u)}{P(\|X\| > u)} \rightarrow \int_{\mathbb{S}_1} \|A\theta\|^\alpha H(d\theta) \quad (u \rightarrow \infty).$$

If $H(\{\theta \in \mathbb{S}_1 : A\theta \neq 0\}) > 0$, this limit is positive and AX is regularly varying in \mathbb{B}_2 with index α and spectral measure H_A

$$\int_{\mathbb{S}_2} g(\theta) H_A(d\theta) = \frac{1}{\int_{\mathbb{S}_1} \|A\theta\|^\alpha H(d\theta)} \int_{\mathbb{S}_1} g\left(\frac{A\theta}{\|A\theta\|}\right) \|A\theta\|^\alpha H(d\theta).$$

for H_A -integrable $g : \mathbb{S}_2 \rightarrow \mathbb{R}$.

The transformed spectral measure can be simulated from by a rejection algorithm

The expression for H_A has the following probabilistic meaning:

$$H_A = \mathcal{L} \left(\frac{A\Theta}{\|A\Theta\|} \mid U \leq \frac{\|A\Theta\|^\alpha}{\|A\|^\alpha} \right).$$

- ▶ Θ is a random element in \mathbb{S}_1 with distribution H
- ▶ $U \sim \text{Uniform}(0, 1)$ independent of Θ

Rejection algorithm

Generating a random draw Θ_A from H_A :

1. Draw $\Theta \sim H$ and $U \sim \text{Uniform}(0, 1)$ independently.
2. If $U \leq \|A\Theta\|^\alpha / \|A\|^\alpha$, then return $\Theta_A = A\Theta / \|A\Theta\|$ and stop.
3. Otherwise, go back to step 1.

Extremes of Stationary Sequences

Introduction

Linear operators and regular variation

Infinite random sums

Linear processes

Example: AR(1) processes

Conclusion

Infinite random sums

Let \mathbb{B}_1 and \mathbb{B}_2 be real, separable Banach spaces.

Tail behavior of the \mathbb{B}_2 -valued infinite random sum

$$X = \sum_n T_n Z_n$$

- ▶ $(Z_n)_{n \in \mathbb{Z}}$ iid random elements in \mathbb{B}_1
- ▶ $T_n : \mathbb{B}_1 \rightarrow \mathbb{B}_2$ bounded linear operators.

Possible extension: *random* linear operators (e.g. random matrices)

[Hult & Samorodnitsky 2008]

Convergence of the series

Put $V(x) = P(\|Z_n\| > x)$. Assume $V \in RV_{-\alpha}$.

Suppose there exists δ with $0 < \delta < \min(\alpha, 1)$ such that

$$\sum_n \|T_n\|^\delta < \infty.$$

As $E[\|Z_n\|^\delta] = \int_0^\infty V(x^{1/\delta}) dx < \infty$, we have

$$E[(\sum_n \|T_n Z_n\|)^\delta] \leq \sum_n \|T_n\|^\delta E[\|Z_n\|^\delta] < \infty,$$

so that the series $X = \sum_n T_n Z_n$ converges absolutely almost surely.

Moreover, the tail of $\|X\|$ is of the same order as the one of $\|Z_n\|$:

$$\frac{P(\|X\| > x)}{V(x)} \leq \frac{P(\sum_n \|T_n\| \|Z_n\| > x)}{V(x)} \rightarrow \sum_n \|T_n\|^\alpha < \infty$$

Regular variation of the summands

Now assume that the common distribution of the random elements Z_n is regularly varying with index α and spectral measure H . We have

$$\lim_{x \rightarrow \infty} \frac{P(\|T_n Z_n\| > x)}{V(x)} = \int_{\mathbb{S}_1} \|T_n \theta\|^\alpha H(d\theta) =: c_n.$$

Moreover, if $c_n > 0$, then $T_n Z_n$ is regularly varying in \mathbb{B}_2 with index α and with spectral measure H_n given by

$$\int_{\mathbb{S}_2} f(\theta) H_n(d\theta) = \frac{1}{c_n} \int_{\mathbb{S}_1} f(T_n \theta / \|T_n \theta\|) \|T_n \theta\|^\alpha H(d\theta)$$

for H_n -integrable functions $f : \mathbb{S}_2 \rightarrow \mathbb{R}$.

The single-shock heuristic (1)

- ▶ Let $(Z_i)_{i \in \mathbb{Z}}$ be an iid sequence in \mathbb{B}_1 .
- ▶ Let $T_i : \mathbb{B}_1 \rightarrow \mathbb{B}_2$, $i \in \mathbb{Z}$, be bounded linear operators.

Proposition

If

- (i) $x \mapsto V(x) = P(\|Z_i\| > x)$ is $RV_{-\alpha}$ for some $\alpha > 0$,
- (ii) $\lim_{x \rightarrow \infty} P(\|T_i Z_i\| > x) / V(x) = c_i \in [0, \infty)$ for all $i \in \mathbb{Z}$,
- (iii) $\sum_i \|T_i\|^\delta < \infty$ for some $0 < \delta < \min(\alpha, 1)$,

then the series $\sum_i T_i Z_i$ is almost surely absolutely convergent and

$$\begin{aligned} & \lim_{x \rightarrow \infty} \frac{1}{V(x)} E \left| I(\|\sum_i T_i Z_i\| > x) - \sum_i I(\|T_i Z_i\| > x) \right| \\ &= \lim_{x \rightarrow \infty} \frac{1}{V(x)} E \left| I(\sum_i \|T_i Z_i\| > x) - \sum_i I(\|T_i Z_i\| > x) \right| \\ &= 0 \end{aligned}$$

The single-shock heuristic (2)

Corollary

$$\begin{aligned}\lim_{x \rightarrow \infty} \frac{P(\|\sum_i T_i Z_i\| > x)}{V(x)} &= \lim_{x \rightarrow \infty} \frac{P(\sum_i \|T_i Z_i\| > x)}{V(x)} \\ &= \lim_{x \rightarrow \infty} \frac{\sum_i P(\|T_i Z_i\| > x)}{V(x)} = \sum_i c_i < \infty.\end{aligned}$$

Extension of Lemma 4.24 in Resnick (1987).

The spectral measure of the series is a mixture of those of the summands

Proposition

If the common distribution of the independent random elements Z_n ($n \in \mathbb{Z}$) is regularly varying with index α and spectral measure H and if $\sum_n \|T_n\|^\delta < \infty$, then

$$\lim_{x \rightarrow \infty} \frac{P(\|\sum_n T_n Z_n\| > x)}{V(x)} = \lim_{x \rightarrow \infty} \frac{P(\sum_n \|T_n Z_n\| > x)}{V(x)} = \sum_n c_n < \infty.$$

If $\sum_n c_n > 0$, then the random series $X = \sum_n T_n Z_n$ is regularly varying with index α too, its spectral measure H_X being given by

$$H_X = \sum_n p_n H_n$$
$$p_n = \frac{c_n}{\sum_k c_k} = \lim_{x \rightarrow \infty} P(\|T_n Z_n\| > x \mid \|\sum_k T_k Z_k\| > x).$$

The spectral measure reflects the biggest-shock heuristic

The spectral measure H_X can be written as

$$\int f dH_X = \frac{\sum_{n \in \mathbb{Z}} E \left[f \left(\frac{T_n(\Theta_Z)}{\|T_n(\Theta_Z)\|} \right) \|T_n(\Theta_Z)\|^\alpha \right]}{\sum_{n \in \mathbb{Z}} E[\|T_n(\Theta_Z)\|^\alpha]},$$

with Θ_Z distributed according to the spectral measure of Z .

Special case: Linear combinations with random coefficients

In case $\mathbb{B}_1 = \mathbb{R}$ we can write $\mathbb{B}_2 = \mathbb{B}$ and the series X is an infinite linear combination of the elements $\psi_i = T_i(1) \in \mathbb{B}$ with random coefficients Z_i :

$$X = \sum_i Z_i \psi_i.$$

The spectral measure of X is equal to

$$H_X = \mathcal{L}(\Theta_Z \psi_N / \|\psi_N\|)$$

with

- ▶ Θ_Z a random variable in $\{-1, +1\}$
- ▶ N an integer-valued random variable independent of Θ_Z and s.t.

$$P(N = n) = p_n = \frac{\|\psi_n\|^\alpha}{\sum_k \|\psi_k\|^\alpha} \quad (n \in \mathbb{Z})$$

Extremes of Stationary Sequences

Introduction

Linear operators and regular variation

Infinite random sums

Linear processes

Example: AR(1) processes

Conclusion

Linear processes with regularly varying innovations

Rather than a single random series, we now study the linear process

$$X_t = \sum_i T_i Z_{t-i}, \quad t \in \mathbb{Z}.$$

with

- ▶ $(Z_n)_{n \in \mathbb{Z}}$ is an iid sequence of $RV(\alpha)$ random elements in \mathbb{B}_1
- ▶ $T_n : \mathbb{B}_1 \rightarrow \mathbb{B}_2$ are bounded linear operators such that $\sum_n \|T_n\|^\delta < \infty$ for some $0 < \delta < \min(\alpha, 1)$

The random series defining X_t converges absolutely and $(X_t)_{t \in \mathbb{Z}}$ is a stationary time series in \mathbb{B}_2 .

The signature of the series given a shock at a certain moment

If $c_n > 0$, where

$$c_n = \int_{\mathbb{S}_1} \|T_n \theta\|^\alpha H(d\theta)$$

we can define a probability measure κ_n on the space $\mathbb{B}_2^{\mathbb{Z}}$ of \mathbb{B}_2 -valued sequences endowed with the product topology by

$$\begin{aligned} \int_{\mathbb{B}_2^{\mathbb{Z}}} f(\theta_{-s}, \dots, \theta_t) \kappa_n(d(\theta_n)_{n \in \mathbb{Z}}) \\ = \frac{1}{c_n} \int_{\mathbb{S}_1} f\left(\frac{T_{-s+n}\theta}{\|T_n\theta\|}, \dots, \frac{T_{t+n}\theta}{\|T_n\theta\|}\right) \|T_n\theta\|^\alpha H(d\theta), \quad (1) \end{aligned}$$

for nonnegative integer s, t and for bounded and continuous

$$f : \mathbb{B}_1^{t+s+1} \rightarrow \mathbb{R}.$$

The spectral process is a mixture over the signature patterns

Proposition

If $\sum_n c_n > 0$, then $(X_t)_{t \in \mathbb{Z}}$ is a regularly varying stationary time series in \mathbb{B}_2 with index α , its spectral process $(\Theta_t)_{t \in \mathbb{Z}}$ having law κ equal to

$$\kappa = \sum_n p_n \kappa_n$$

where $p_n = \frac{c_n}{\sum_k c_k}$

i.e.

$$E[f((\Theta_t)_{t \in \mathbb{Z}})] = \frac{\sum_{n \in \mathbb{Z}} E \left[f \left(\frac{T_{n+t}(\Theta_Z)}{\|T_n(\Theta_Z)\|} \right) \|T_n(\Theta_Z)\|^\alpha \right]}{\sum_{n \in \mathbb{Z}} E[\|T_n(\Theta_Z)\|^\alpha]},$$

Simulating the spectral process

1. Draw a random integer N from $(p_n)_{n \in \mathbb{Z}}$.
2. Independently from N and from each other, draw $\Theta_Z \sim H$ and $U \sim \text{Uniform}(0, 1)$.
3. If $U \leq \|T_N \Theta_Z\|^\alpha / \|T_N\|^\alpha$, then return $\Theta_t = T_{N+t} \Theta_Z / \|T_N \Theta_Z\|$ for all $t \in \mathbb{Z}$ and stop.
4. Otherwise, go back to step 2.

Extremes of Stationary Sequences

Introduction

Linear operators and regular variation

Infinite random sums

Linear processes

Example: AR(1) processes

Conclusion

Autoregressive equation

AR(1) process in $\mathbb{B} = \mathbb{B}_1 = \mathbb{B}_2$:

$$X_t = TX_{t-1} + Z_t, \quad t \in \mathbb{Z}.$$

- ▶ iid innovations Z_t in Banach, $RV(\alpha, H)$
- ▶ $T : \mathbb{B} \rightarrow \mathbb{B}$ bounded linear operator such that $\|T^m\| < 1$ for some integer $m \geq 1$

Note: fairly general, since by considering sequence spaces, an arbitrary linear process can be represented as the image of a linear operator applied to an AR(1) process

The AR(1) equation has a regularly varying solution

The AR(1) equation has a stationary solution given by

$$X_t = \sum_{n \geq 0} T^n Z_{t-n}, \quad t \in \mathbb{Z},$$

The tail of $\|X_t\|$ satisfies

$$\lim_{x \rightarrow \infty} \frac{P(\|X_t\| > x)}{P(\|Z_0\| > x)} = \sum_{n \geq 0} \int_{\mathcal{S}} \|T^n \theta\|^\alpha H(d\theta)$$

$(X_t)_{t \in \mathbb{Z}}$ is regularly varying with index $\alpha > 0$ and with spectral process as described above.

- ▶ $p_n = 0$ for all $n < 0$
- ▶ If $p_{n_0} = 0$ for some integer $n_0 \geq 1$, then $p_n = 0$ for all $n \geq n_0$

Simulating the spectral process of an AR(1) process

1. Draw a random nonnegative integer N from $(p_n)_{n \geq 0}$.
2. Independently from N and from each other, draw $\Theta_Z \sim H$ and $U \sim \text{Uniform}(0, 1)$.
3. If $U \leq \|T^N \Theta_Z\|^\alpha / \|T^N\|^\alpha$, then return

$$\Theta_{-N} = \frac{\Theta_Z}{\|T^N \Theta_Z\|}, \quad \Theta_{-N+h} = \begin{cases} T^h \Theta_{-N} & \text{if } h > 0, \\ 0 & \text{if } h < 0. \end{cases}$$

4. Otherwise, go back to step 2.

Extremes of Stationary Sequences

Introduction

Linear operators and regular variation

Infinite random sums

Linear processes

Example: AR(1) processes

Conclusion

Main findings

- ▶ Regular variation is preserved by **bounded linear operators**
- ▶ Tails of random series with independent, regularly varying components governed by the **single-shock heuristic**
- ▶ **AR(1) processes**: simple structure of the spectral process, readily simulated

Thank you!

References (1)

- ▶ Basrak, B., Krizmanić, D., Segers, J. (2011), *Ann. Probab.* 40, 2008–2033.
- ▶ Bartkiewicz, K., Jakubowski, A., Mikosch, T., Wintenberger, O. (2011) *Probab. Th. Rel. Fields* 150, 337–372.
- ▶ Basrak, B., Segers, J. (2009), *Stoch. Process. Applic.* 119, 1055–1080
- ▶ Bortot, P., Coles, S.G. (2000) *Bernoulli* 6, 183–190.
- ▶ Bortot, P., Coles, S.G. (2003) *J. R. Statist. Soc. B* 65, 851–867.
- ▶ Davis, R.A., Hsing, T. (1995), *Ann. Probab.* 23, 879–917.
- ▶ Davis, R.A., Mikosch, T. (1998), *Ann. Statist.* 26, 2049–2080.
- ▶ Davis, R.A., Mikosch, T. (2006), *Stoch. Process. Applic.* 118, 560–584.
- ▶ Davis, R.A., Mikosch, T. (2009), *Bernoulli* 15, 977–1009.
- ▶ Davis, R.A., Resnick, S.I. (1985), *Ann. Probab.* 13, 179–195.

References (2)

- ▶ De Haan, L., Resnick, S.I., Rootzén, H., & de Vries, C. (1989) *Stoch. Process. Applic.* 32, 213–224.
- ▶ Drees, H., Rootzén, H. (2010), *Ann. Statist.* 38, 2145–2186.
- ▶ Hult, H., Lindskog, F. (2005) *Stoch. Process. Applic.* 115, 249–274.
- ▶ Hult, H., Lindskog, F. (2006) *Publ. Inst. Math. (Beograd) (N.S.)* 80, 121–140.
- ▶ Hult, H., Samorodnitsky, G. (2008) *Bernoulli* 14, 838–864.
- ▶ Meinguet, T., Segers, J. (2010) arXiv:1001.3262.
- ▶ Mikosch, T., Samorodnitsky, G. (2000) *Ann. Appl. Probab.* 10, 1025–1064.
- ▶ Leadbetter, R. (1983) *Z. Wahrscheinlichkeitsth.* 65, 291–306.
- ▶ Mikosch, T., Wintenberger, O. (2012a) *Probab. Th. Rel. Fields* DOI 10.1007/s00440-012-0445-0.
- ▶ Mikosch, T., Wintenberger, O. (2012b) Mimeo.
- ▶ Nandagopalan, S. (1994) *J. Research of the National Institute of Standards and Technology* 99, 543–550.

References (3)

- ▶ O'Brien, G.L. (1987) *Ann. Probab.* 15, 281–291.
- ▶ Perfekt, R. (1994) *Ann. Appl. Probab.* 4, 529–548.
- ▶ Resnick, S. I. (1987) *Extreme Values, Regular Variation and Point Processes*, Springer.
- ▶ Resnick, S. I. (2007) *Heavy-Tailed Phenomena*, Springer.
- ▶ Resnick, S. I., Zeber, D. (2011) arXiv:...
- ▶ Rootzén, H. (1988) *Adv. Appl. Probab.* 20, 371–390.
- ▶ Segers, J. (2003) *Adv. Appl. Probab.* 35, 1028–1045.
- ▶ Segers, J. (2005) *Statist. Probab. Letters* 74, 330–336.
- ▶ Segers, J. (2007) arXiv:0701411.
- ▶ Smith, R. (1992) *J. Appl. Probab.* 29, 37–45.
- ▶ Wintenberger, O. (2012) *Mémoire d'Habilitation*, Université Paris–Dauphine.
- ▶ Yun, S. (2000) *J. Appl. Probab.* 37, 29–44.