Modern Optimization Theory: Quasi-Concave Programming

1. Preliminaries

- The theory of concave programming, as developed by Kuhn and Tucker, is a very convenient and powerful tool in optimization theory.
 - For many economic applications, however, it is difficult to justify the assumption of *concavity* of the objective and constraint functions.
- In many such cases, one finds it easier to defend the assumption that these functions are *quasi-concave*.
 - It is with these economic applications in mind that Arrow and Enthoven developed the theory of quasi-concave programming.
- In what follows, we cover the elements of this theory by focusing on its two main results.
 - One result provides conditions under which a point satisfying the Kuhn-Tucker conditions is a point of constrained global maximum.
 - Another result provides conditions under which a point of constrained global maximum satisfies the Kuhn-Tucker conditions.

• Modification in the Maximization Problem and the Kuhn-Tucker conditions:

- So far we were concerned with the following constrained maximization problem:

Maximize
$$f(x)$$

subject to $g^{j}(x) \ge 0$, for $j = 1, 2, ..., m$
and $x \in X$ (P)

where

- X is a non-empty subset of
$$\Re^n$$
, and

- f, g^j (j = 1, 2, ..., m) are functions from X to \Re .

- And the corresponding Kuhn-Tucker conditions are:

- The Kuhn-Tucker Conditions:

Let X be an open set in \Re^n , and f, g^j (j = 1, 2, ..., m) be continuously differentiable on X. A pair $(\hat{x}, \hat{\lambda}) \in (X \times \Re^m_+)$ satisfies Kuhn-Tucker conditions if (a) $\frac{\partial f}{\partial x_i}(\hat{x}) + \sum_{i=1}^m \hat{\lambda}_j \frac{\partial g^j}{\partial x_i}(\hat{x}) = 0, i = 1, 2, ..., n;$ (b) $g^j(\hat{x}) \ge 0$, and $\hat{\lambda}_j g^j(\hat{x}) = 0, j = 1, 2, ..., m.$

- The maximization problem that we discuss under quasi-concave programming is somewhat more restrictive in theory than the one considered under concave programming, but not in practice for most applications.
- The optimization problem is:

Maximize
$$f(x)$$

subject to $g^{j}(x) \ge 0$, for $j = 1, 2, ..., m$
and $x \in \Re_{+}^{n}$.

where f, g^j (j = 1, 2, ..., m) are functions from \Re^n to \Re .

- The (Modified) Kuhn-Tucker Conditions:

A pair $(\hat{x}, \hat{\lambda}) \in (\Re^n_+ \times \Re^m_+)$ satisfies the Kuhn-Tucker conditions if (i) $\frac{\partial f}{\partial x_i}(\hat{x}) + \sum_{j=1}^m \hat{\lambda}_j \frac{\partial g^j}{\partial x_i}(\hat{x}) \le 0, i = 1, 2, ..., n;$ (ii) $\hat{x}_i \left[\frac{\partial f}{\partial x_i}(\hat{x}) + \sum_{j=1}^m \hat{\lambda}_j \frac{\partial g^j}{\partial x_i}(\hat{x}) \right] = 0, i = 1, 2, ..., n;$ (iii) $\hat{x}_i \ge 0, i = 1, 2, ..., n;$ (iv) $g^j(\hat{x}) \ge 0, j = 1, 2, ..., m;$ (v) $\hat{\lambda}_j g^j(\hat{x}) = 0, j = 1, 2, ..., m;$ (vi) $\hat{\lambda}_i \ge 0, j = 1, 2, ..., m.$

- #1. Show that the (modified) Kuhn-Tucker conditions ((i) (vi)) for problem (Q) are equivalent to the Kuhn-Tucker conditions ((a) - (b)) for problem (P).
 - The constraint set for problem (Q) is defined as

$$C = \left\{ x \in \Re^n_+ : g^j(x) \ge 0, \text{ for } j = 1, 2, ..., m \right\}.$$

2. The Sufficiency Theorem of Arrow-Enthoven

• Lemma 1:

Suppose f, g^j (j = 1, 2, ..., m) are continuously differentiable functions on \Re^n . Suppose there is a pair $(\hat{x}, \hat{\lambda}) \in (\Re^n_+ \times \Re^m_+)$ such that $(\hat{x}, \hat{\lambda})$ satisfies the Kuhn-Tucker conditions. If each g^j is quasi-concave, then

 $x \in C$ implies $(x - \hat{x}) \cdot \nabla f(\hat{x}) \leq 0.$

- Proof: To be discussed in class.

– Hints:

$$\circ (x - \hat{x}) \cdot \nabla f(\hat{x}) = (x - \hat{x}) \cdot \left[\nabla f(\hat{x}) + \sum_{j=1}^{m} \hat{\lambda}_j \nabla g^j(\hat{x})\right] - (x - \hat{x}) \cdot \left[\sum_{j=1}^{m} \hat{\lambda}_j \nabla g^j(\hat{x})\right].$$

- Use the Kuhn-Tucker conditions to show that the R.H.S $\leq -(x - \hat{x}) \cdot [\sum_{j=1}^{m} \hat{\lambda}_j \nabla g^j(\hat{x})].$

• If $\hat{\lambda}_j > 0$ for some j, use the Kuhn-Tucker conditions and the quasi-concavity of g^j to argue that $(x - \hat{x}) \cdot \hat{\lambda}_j \nabla g^j$ $(\hat{x}) \ge 0$ for that j.

• Relevant Index:

An index $k \in \{1, 2, ..., n\}$ is called a *relevant index* if there exists $x^* \in C$ such that $x_k^* > 0$.

• Theorem 1:

Suppose f, g^j (j = 1, 2, ..., m) are continuously differentiable quasi-concave functions on \Re^n . Suppose there is a pair $(\hat{x}, \hat{\lambda}) \in (\Re^n_+ \times \Re^m_+)$ such that $(\hat{x}, \hat{\lambda})$ satisfies the Kuhn-Tucker conditions. Suppose further that at least one of the following conditions is satisfied:

(a)
$$\frac{\partial f}{\partial x_i}(\hat{x}) < 0$$
 for some $i \in \{1, 2, ..., n\}$;

(b)
$$\frac{\partial f}{\partial x_i}(\hat{x}) > 0$$
 for some *i* which is a relevant index;

(c) f is concave on \Re^n .

Then \hat{x} solves problem (Q).

- Proof: To be discussed in class.

• **Proof of Theorem 1(a):** There is some index k, such that $\frac{\partial f}{\partial x_k}(\hat{x}) < 0$. Let e^k be the k-th unit vector, and define $\bar{x} = \hat{x} + e^k$. Then $\bar{x} \in \Re^n_+$, and

$$(\bar{x} - \hat{x}) \cdot \nabla f(\hat{x}) < 0.$$
⁽¹⁾

Let x be an arbitrary vector in C. We have to show that $f(x) \le f(\hat{x})$. Define, for $0 < \theta < 1$, $x(\theta) = \theta \bar{x} + (1 - \theta) x$, and $y(\theta) = \theta \bar{x} + (1 - \theta) \hat{x}$. Then, using $\theta > 0$ and (1), we have

$$(y(\theta) - \hat{x}) \cdot \nabla f(\hat{x}) = \theta(\bar{x} - \hat{x}) \cdot \nabla f(\hat{x}) < 0.$$

Also, by Lemma 1,

$$(x(\theta) - y(\theta)) \cdot \nabla f(\hat{x}) = (1 - \theta)(x - \hat{x}) \cdot \nabla f(\hat{x}) \le 0.$$

Combining the above two inequalities we get $(x(\theta) - \hat{x}) \cdot \nabla f(\hat{x}) < 0$, and since f is quasi-concave, we have $f(x(\theta)) < f(\hat{x})$. Finally, letting $\theta \to 0$, we get $f(x) \le f(\hat{x})$.

• Proof of Theorem 1(b):

Suppose condition (b) holds. If condition (a) still holds, we are already done. So assume that condition (a) does not hold. That is, $\nabla f(\hat{x}) \ge 0$, and $\frac{\partial f}{\partial x_k}(\hat{x}) > 0$, for some index k which is a relevant index. Thus, there is $x^* \in C$ such that $x_k^* > 0$. Using Lemma 1,

$$\hat{x} \cdot \nabla f(\hat{x}) \ge x^* \cdot \nabla f(\hat{x}) > 0.$$
(2)

Let x be an arbitrary vector in C. Then, for $0 < \theta < 1$,

 $\left(\theta x\right)\cdot \nabla f\left(\hat{x}\right) \leq \left(\theta \hat{x}\right)\cdot \nabla f\left(\hat{x}\right) < \hat{x}\cdot \nabla f\left(\hat{x}\right).$

Then quasi-concavity of f implies $f(\theta x) < f(\hat{x})$. Finally, letting $\theta \to 1$, we get $f(x) \le f(\hat{x})$.

• Corollary 1:

Suppose f, g^j (j = 1, 2, ..., m) are continuously differentiable quasi-concave functions on \Re^n . Suppose there is a pair $(\hat{x}, \hat{\lambda}) \in (\Re^n_+ \times \Re^m_+)$ such that $(\hat{x}, \hat{\lambda})$ satisfies the Kuhn-Tucker conditions. Suppose there is $x^* \gg 0$, such that $g^j(x^*) \ge 0$, for j = 1, 2, ..., m, and $\nabla f(\hat{x}) \ne 0$. Then \hat{x} solves problem (Q).

- Proof: To be discussed in class.

• Slater's Condition:

We say that Slater's condition holds if there exists $\bar{x} \in C$ such that $g^{j}(\bar{x}) > 0$, for j = 1, 2, ..., m.

• Corollary 2:

Suppose f, g^j (j = 1, 2, ..., m) are continuously differentiable quasi-concave functions on \Re^n . Suppose there is a pair ($\hat{x}, \hat{\lambda}$) $\in (\Re^n_+ \times \Re^m_+)$ such that ($\hat{x}, \hat{\lambda}$) satisfies the Kuhn-Tucker conditions. Suppose Slater's condition is satisfied, and $\nabla f(\hat{x}) \neq 0$. Then \hat{x} solves problem (Q).

- Proof: To be discussed in class.

3. The Necessity Theorem of Arrow-Enthoven

• Theorem 2:

Suppose f, g^j (j = 1, 2, ..., m) are continuously differentiable functions on \Re^n . Suppose g^j (j = 1, 2, ..., m) are quasi-concave on \Re^n , and there is $x^* \in C$ such that $g^j(x^*) > 0$, for j = 1, 2, ..., m. If $\hat{x} \in \Re^n_+$ solves problem (Q), and for each j = 1, 2, ..., m, $\nabla g^j(\hat{x}) \neq 0$, then there is $\hat{\lambda} \in \Re^m_+$ such that $(\hat{x}, \hat{\lambda})$ satisfies the Kuhn-Tucker conditions.

#2. Example 1:

Suppose a, b, c > 0. Consider the following minimization problem:

 $\left.\begin{array}{ll} \text{Minimize} & ax_1 + bx_2 \\ \text{subject to} & x_1x_2 \ge c, \\ \text{and} & (x_1, x_2) \in \Re^2_+. \end{array}\right\}$

Find out the solution(s) to the minimization problem.

 – (Mention clearly which theorem you are using, and demonstrate carefully that all the required conditions of that theorem are satisfied.)

#3. Example 2:

Consider the following maximization problem:

Maximize $x_1 + x_1x_2 + x_2$ subject to $1 - \alpha x_1 - \beta x_2 \ge 0, \alpha > 0, \beta > 0$ and $(x_1, x_2) \in \Re^2_+$.

- (a) Take the *sufficiency route* to find the solution(s) to this problem. Explain your steps clearly.
- (b) Take the *necessary route* to find the solution(s) to this problem. Explain your steps clearly.

References

- Must read the following sections from the textbook:
 - Section 21.5 (pages 532 537): Concave Programming.
- This material is primarily based on
 - 1. Arrow, K.J. and Enthoven, A.C., (1961), "Quasi-concave Programming," *Econometrica*, pages 779-800.